# OPERATION MANUAL

# STEREO TRIGGERSCOPE

MODEL 5502A

KIKUSUI ELECTRONICS CORPORATION

# Power Requirements of this Product

Power requirements of this product have been changed and the relevant sections of the Operation Manual should be revised accordingly.  (Revision should be applied to items indicated by a check mark .)				
☐ Input voltage				
The input voltage of this product is to to	VAC, VAC. Use the product within this range only.			
☐ Input fuse				
The rating of this product's input fuse is	A,VAC, and			
WA	RNING			
	k, always disconnect the AC the switch on the switchboard k or replace the fuse.			
characteristics suitable for with a different rating or o	naving a shape, rating, and r this product. The use of a fuse one that short circuits the fuse , electric shock, or irreparable			
☐ AC power cable				
	ables described below. If the cable has no power plug mals to the cable in accordance with the wire color			
*	RNING er crimp-style terminals alified personnel.			
☐ Without a power plug	☐ Without a power plug			
Blue (NEUTRAL)	White (NEUTRAL)			
Brown (LIVE)	Black (LIVE)			
Green/Yellow (GND)	Green or Green/Yellow (GND)			
☐ Plugs for USA	☐ Plugs for Europe			
	G. C.			
Provided by Kikusui agents  Kikusui agents can provide you with s  For further information, contact your I				



# TABLE OF CONTENTS

			PAGE
1.	GEN	ERAL	1
	1.1	Description	1
	1.2	Features	1
2.	SPE	CIFICATIONS	3
3.	OPE	RATING INSTRUCTIONS	10
	3.1	Explanation of Front Panel	10
	3.2	Explanation of Rear Panel	15
	3.3	Explanation of Bottom	15
	3.4	Precautions in Operation	18
	3.5	Line Voltage Conversion	19
4.	OPE	RATING PROCEDURE	21
	4.1	Preliminary Procedure	21
	4.2	Dual-trace Operation	23
	4.3	STEREO/X-Y Operation	25
	4.4	Only X-Y Operation	27
5.	METH	ODS OF MEASUREMENTS	28
	5.1	Connection Method of Input Signal	28
	5.2	Voltage Measurement	32
	5.3	Current Measurement	34
	5.4	Time Measurement	34
	5.5	Frequency Measurement	35
	5.6	Measurement of Phase Difference	37
	5.7	Measurement of Pulse Waveform Characteristics	44

			PAGE
6.	CALI	BRATION	47
	6.1	General	47
	6.2	Check and Adjustment of DC Power Supply	47
	6.3	Adjustment of Vertical Axis	52
	6.4	Adjustment for Horizontal Dual-trace Operation	55
	6.5	Adjustment of Time Base	58
	6.6	Adjustment of X-axis	59
	6.7	Calibration of Probe	60
7.	Bloc	k Diagram	

### 1. GENERAL

### 1.1 Description

Kikusui Model 5502A Stereo Triggerscope is a trigger-synchoronized dual-trace portable oscilloscope with a high-brightness cathode-ray tube of 133 mm (5.24 in.) diameter. Its sensitivity is 10 mV/DIV, bandwidth 5 MHz, and maximum sweep speed 1 µsec/DIV. Its operation is not only selectable between vertical dual-channel mode and horizontal dual-channel mode but also simultaneous displaying of X-Y with vertical dual-channel or horizontal dual-channel mode with its mode selector switch. It can be used for research and development of various electronic devices as well as for production and maintenance service.

### 1.2 Features

o Front frame made of aluminium diecast:

To provide a neat external view and a sufficient mechanical strength for maintenance service, the front frame is made of aluminium diecast.

o Dual-channel mode selector switch incorporated:

The 5502A is incorporated with a mode selector switch for selection between vertical dual-channel operation and horizontal dual-channel operation. Also be able to display of X-Y with vertical dual-channel or horizontal dual-channel mode simultaneously, providing an another advantageous feature in observation of various types of waveforms.

### o High-brightness CRT:

(i) (j) The 5502A employs a CRT of an excellent beam transmission factor, providing a sufficient trace brightness even at the highest sweep speed.

## o Stable acceleration voltage:

The acceleration voltage of the 5502A is very stable against line voltage variation, as this high voltage is regulated with a unique control circuit.

## o Rotation coil for trace leveling:

The 5502A employs a rotation coil which enables you to adjust (rotate) the base line for leveling when it has become slanted by terrestrail magnetism. Adjustment can be done at the front panel.

## o Automatic CHOP/ALT switching:

The operating mode is automatically switched between CHOP mode and ALT mode in conformity with the sweep speed (linked to the TIME/DIV switch), thereby preventing troublesome manual switching between the two modes when in the dual-channel operation.

# o Wider triggering frequency range:

The 5502A has a wide triggering frequency range of  $10~\mathrm{Hz}$  -  $5~\mathrm{MHz}$ , enabling low frequency signal waveform observation and phase measurement with a trigger frequency of down to  $10~\mathrm{Hz}$ .

### o Indivisual X-Y operation:

Simply by switching the operation of the vertical axis to X-Y only mode. The scope can be worked into an X-Y scope indivisually with CHL input for X and CHR input for Y-axis.

#### SPECIFICATIONS

## Vertical Axis

	_	2
Item	Specification	Remarks
Sensitivity ranges	10 mV/DIV - 1 V/DIV	1-10 sequency, 4-ranges including GND
Sensitivity accuracy	Better than ±5% of panel-indicated value.	VARIABLE knob is set in CAL position, 1 kHz, at 4 or 5 DIV
Continuously- variable sensitivity adjustment	10 times or over	Covers between ranges with VARIABLE knob.
Frequency response	DC: DC - 5 MHz, within -3 dB AC: 2 Hz - 5 MHz, within -3 dB	50 kHz, 8 DIV reference.
Rise time	Approx. 70 nsec	
Input impedance	1 M $\Omega$ ±2%, approx. 30 pF ± 2 pF	Parallel. Probe can be used.
Input terminals	BNC receptacles	
Maximum allowable input voltage	400 Vp-p, for 1 minute.	DC + AC peak, frequency not higher than 1 kHz.
Input coupling selection	AC, DC	
DC balance	Less than ± 0.5 DIV	,
_	_,	

Item		Sn	ecification	Remarks
				ROMAL NO
Operation modes of	CHL Si		ngle-channel mode	
vertical axis	CHR	Si	ngle-channel mode	
	STEREO		CHOP mode (10 msec/DIV - 1 msec/DIV)	When trigger source is CHL or CHL + CHR
			ALT mode (100 μsec/DIV - 1 μsec/DIV)	When trigger source is NORM, operation is ALT mode for all TIME/DIV ranges.
	Н		Horizontal dual- channel operation	
	V		Vertical dual- channel operation	
Chop frequency	Not high		100 kHz	
Overshoots			ner than 3%	100 kHz square wave,
Isolation between channels			or better	100 kHz, 8 DIV
Linearity	When a signal displayed for 4 DIV in CRT screen center is vertically shifted for the full screen range, vertical amplitude change is within ±0.2 DIV.			At frequency not higher than 100 kHz. Including linearity of CRT.

# o Trigger

	<del></del>		
Item		Specification	Remarks
Trigger signal	CHL	Triggered with CHL signal alone.	
	CHL + CHR	Triggered with the sum of the signals of CHL and CHR.	CHL and CHR signals must be of the same frequency.
	NORM	Triggered with CHL and CHR signals.	
	EXT	Triggered with external signal.	
Sensitivity	INT	10 Hz - 5 MHz, 0.5 DIV or over	In terms of displayed signal amplitude on the CRT.
	EXT	10 Hz - 5 MHz, 0.5 Vp-p or over	
Trigger system	AUTO	trigger sweep	When no signal is applied, the sweep occurs in FREE RUN mode. For input signal of 10 Hz or higher, the above trigger sensitivity specification is met.
Polarity (SLOPE)	"+" oı	nly	
Coupling	ĄC		
-			

Item	Specification	Remarks
EXT trigger input impedance	Approx. 1 M $\Omega$ , 50 pF or less	Parallel
Maximum allowable input impedance	100 Vp-p	DC + AC peak. Frequency not higher than 1 kHz.
External input terminals	BNC receptacles	

# Horizontal Axis

Item	5	Specification	Remarks
Sweep time	l μsec	- 10 msec/DIV	1, 10, step 5 ranges
Continuously variable range of sweep time	10 time	es or over	Covers between ranges with VARIABLE knob.
Sweep time accuracy	indicat	than ±5% of panel ed value VARIABLE t in CAL position	
Sweep directions	MODE V From left end to right end on CRT screen for both CHL and CHR		
	MODE H	From left end to center for CHL and from right end to center for CHR	From left end to center for CHL and from center to right end for CHR also are possible by changing internal connections.

Item	Specification	Remarks
X-Y mode	CHL for X (horizontal) CHR for Y (vertical)	
Sensitivity	The same spec's as CHL of the vertical axis.	
Frequency response	DC: DC - 1 MHz, within -3 dB  AC: 2 Hz - 1 MHz, within -3 dB	50 kHz, 10 DIV reference
Input impedance	The same spec's as CHL of the vertical axis	
Maximum allowable input voltage	The same spec's as CHL of the vertical axis	
X-Y phase difference	Within 3° at 50 kHz	

# Calibration Voltage

Item	Specification	Remarks
Waveform	Square wave, positive going	
Output voltage	1 Vp-p, ±3%	
Frequency	1 kHz ±25%	
Duty ratio	45 : 55 - 55 : 45	
Output terminal	Chip terminal	

# Cathode-ray Tube

Item	Specification	Remarks
Shape	Round, 133 mm	(5.24 in.)
Fluorescent screen	B31	Green
Acceleration voltage	Approx. 1600 V	Regulated
Area (gratucule)	8 × 10 DIV	1 DIV = 9.5 mm (0.37 in.)
Unblanking	AC-coupling	at Gl of the CRT

# Power Requirements

Item	Specification	Remarks
AC line voltage	100, 110, 120, 220, 230, or 240 V. (Within ±10% of each nominal voltage)	Selectable with connector and pins of voltage selector board
Frequency	50 - 60 Hz	
Power consumption	Approx. 20 VA	

### Mechanical Specification

Item	Specification	Remarks
Overall dimensions	244 W × 184 H × 370 D mm (9.61 W × 7.24 H × 14.57 D in.) 250 W × 210 H × 425 D mm (9.84 W × 8.27 H × 16.73 D in.)	Maximum dimensions
Weight	Approx. 7 kg (15.4 1bs)	

### Ambient Conditions

Item	Specification	Remarks
Specification conditions	5°C - 35°C (41°F - 95°F), 85% or less	Conditions for meeting specification performances
Operating conditions	0°C - 40°C (32°F - 104°F),	Conditions for instrument operation

# COMPOSITION

960 BNC Type Probe (10:1, 1:1)

A complete set of the instrument is composed of the following items:

# 3. OPERATING INSTRUCTIONS

# 3.1 Explanation of Front Panel (See Fig. 1)

No.	Panel mark	Description
1	POWER ON-OFF	AC mains power ON-OFF switch.
2	INTEN	Trace intensity control. Trace becomes brighter as this knob is turned clockwise.
3		Indicates ON/OFF state of instrument power.
4	TRACE ROTATION	Semi-fixed resistor for level (horizontal inclination) adjustment of base line which may be inclined by terrestrial magnetism, etc.  Adjust with a fine screwdriver.
5	FOCUS	So adjust this knob that the trace displayed on the screen becomes sharpest.
6	CALIB 0.5 Vp-p	Output terminal which provides a calibration voltage used for probe calibration. The calibration voltage is 0.5 Vp-p (±5%), positive-going square wave of approx. 1 kHz.
7	<u></u>	Ground terminal
8	POSITION	For vertical positioning of CHR (or Y-axis).  The trace moves upward as this knob is turned clockwise, and vice versa.

NO.	Panel mark	Description	
9 10 11 12	MODE	Pushbutton switches for selecting operating modes of CHL and CHR amplifiers.	
12	CHL 12	CHL: CHL vertical amplifier alone operates, as a single-channel oscilloscope.	
	CHR (1)	CHR: CHR vertical amplifier alone operates, as a single-channel oscilloscope.	
	(BOTH IN)	STEREO: When both CHL and CHR buttons are pressed at the same time, CHL and	
		CHR vertical amplifiers operate in CHOP or ALT mode and the instrument operates as a dual-channel oscilloscope. Switching between CHOP and ALT modes is automatically done being linked to TIME/DIV switch.	
	STEREO/X-Y	X-Y: X-Y operation with CHL as X-axis (horizontal) and CHR as Y-axis (vertical). Also be able to display of X-Y with verticall dual-channel or horizontal dual- channel mode simultaneously.	
	X-Y only	When both CHR (1) and STEREO/X-Y (10) buttons are pressed at the same time.  The scope operates only X-Y mode.	
	н 🛚 v 💻 🧐	H : Horizontal dual-trace oscilloscope with  CHL and CHR signals displayed to left and right in horizontal direction.  V : Regular dual-trace oscilloscope	
13	POSITION	For vertical positioning of CHR. The function is the same with that of NO. $(8)$	

No.	Panel mark	Description
14 16	VOLTS/DIV	Rotary switch for sensitivity selection of CHL (or X-axis) and CHR (or Y-axis) channels covering four ranges of 10 mV/DIV to 1 V/DIV and including GND.  Used to obtain appropriate deflection amplitudes on CRT screen. When set at GND, input circuit is made open and amplifier input is grounded, providing a convenient means of checking the base line level of trace.
15)	VARIABLE	Continuously-variable adjustment of vertical sensitivity of CHL (or X-axis) and CHR (or Y-axis), covering between ranges selected by VOLTS/DIV switch (14) or 16).  (At the CAL position, sensitivity is calibrated to the value indicated by VOLTS/DIV switch.
(B) (D)	CHL (X) CHR (Y)	Input terminals for CHL (X-axis) and CHR (Y-axis). When in X-Y operation, CHL is used as X-axis (horizontal axis). The signal can be applied with 959A BNC probe or type 942A terminal adaptor.
@ 2D	AC	Pushbutton switch for selection of input coupling of vertical amplifier. The popped up state ( ) is for AC coupling and the depressed state ( ) for DC coupling.

No.	Panel mark	Description	
22	EXT TRIG IN	Input terminal for external trigger signal.  When the TRIGGERING switch 26 is set in the EXT state, the sweep is triggered by the signal applied to this terminal.	
23	TIME/DIV	Horizontal sweep time selector switch for 10 msec/DIV - 1 µsec/DIV in 5 ranges.	
24	VARIABLE	Continuously-variable adjustment of sweep time, covering between ranges selected by TIME/DIV switch 23.  (When this knob is set in the CAL position, the sweep time is calibrated at the value indicated by the TIME/DIV switch.	
25)	LEVEL  - ← 0 → +	Trigger level adjustment for displaying stationary waveform. The trigger level rises as this knob is turned toward → + and it falls as the knob is turned toward - ←.	
26 27 28	TRIGGERING  (BOTH IN)  CHL + CHR INT  CHL NORM EXT  CHL NORM EXT  28 27 26	Triggering switch circuit consisting of trigger source.  INT: For internal trigger source.  Triggering is done with signal selected by switch 27 or 28.  EXT: Trigger source is external (the signal applied through TRIG IN terminal 22 is used as the trigger signal).	

No.	Panel mark	Description	
		_ma_ CHL: Signal of CHL is used as trigger source signal.	
		_mm_ NORM: Signals of CHL and CHR are used as trigger source signals.	
		(BOTH IN) CHL + CHR: Sum of signals of CHL and CHR	
		is used as trigger source signal.  Signals of CHL and CHR must be  of the same repetition frequency  and phase difference within 180°.	
29	←→ POSITION	Horizontal positioning knob. The displayed waveform moves rightward as this knob is turned clockwise, and vice versa.	

# 3.2 Explanation of Rear Panel (See Fig. 2)

No.	Panel mark	Description
34	-	AC power cord of the oscilloscope
35)		Studs for using the oscilloscope in a vertical attitude. Also used as AC power cord take-up posts.
36	(FUSE)	Fuse holder. Fuse rating is 0.5 A for 100 V system AC line or 0.3 A for 200 V system AC line. For replacing the fuse, remove the cap by turning it counterclockwise.

# 3.3 Explanation of Bottom (See Fig. 3)

No.	Panel mark	Description
37	ASTIG	Semi-fixed resistor for astigmatism control  So adjust this control is conjunction with the  FOCUS control that the trace is made sharpest.
:38	and the second s	Studs which are used also for fixing the stand.
39		Stand for setting the oscilloscope in a slanted attitude for ease of observation. Do not use this stand when oscilloscope camera and adaptor are used.

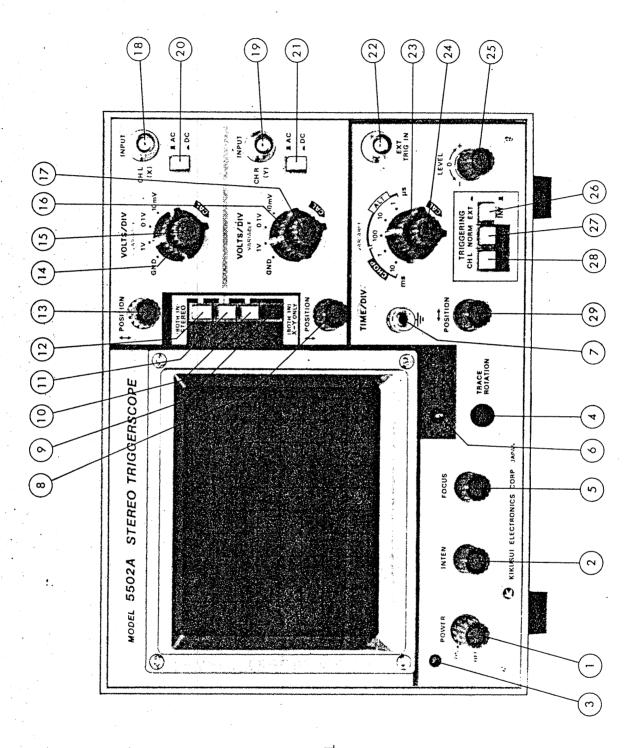


Fig. 1

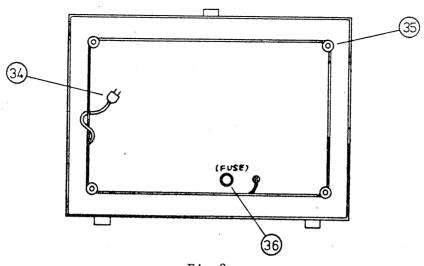


Fig.2

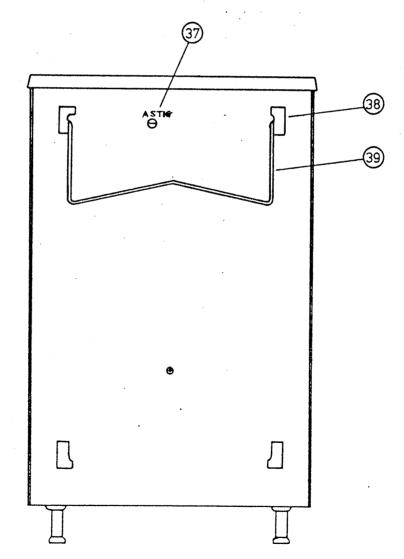


Fig. 3

## 3.4 Precautions in Operation

### o Line voltage:

The oscilloscope is set for operation on a 100 V ±10% AC line voltage. To operate the oscilloscope on other AC line voltage, it must be modified as explained in Para. 3.5 "AC Line Voltage Conversion." Note that the oscilloscope will not operate properly or may be damaged if it is operated on a wrong AC line voltage.

### o Ambient temperature:

The ambient temperature range for normal operation of the oscilloscope is  $5^{\circ}C - 35^{\circ}C$  ( $41^{\circ}F - 9.5^{\circ}F$ ).

#### o Environments:

The oscilloscope must not be operated or stored in high temperature, high humidity atmosphere for a long period since such will cause troubles or shorten the instrument life.

If the oscilloscope is operated in a strong electric or magnetic field, the displayed waveform may be distorted.

### . o Intensity of CRT beam:

Do not make the CRT image excessively bright and do not leave the spot stationary for a long period, lest the CRT screen should be "burnt" shortening its life.

### o Allowable voltages of input terminals:

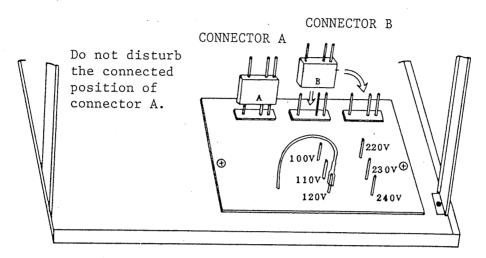
The maximum allowable voltages of input terminals and probe (option) are as shown in the below table. Note that the circuit may be damaged if a voltage larger than the allowable maximum is applied.

Terminal	Allowable maximum input voltage
Vertical input terminal	400 Vp-p (DC + ACp, within l minute)
Probe (960 BNC) (option)	600 Vp-p (DC + ACp, within 1 minute)
EXT TRIG IN terminal '	100 Vp-p (DC + ACp)
Repetion frequency of AC	Not higher than 1 kHz

## 3.5 Line Voltage Conversion

As a general rule the 5502A Oscilloscope is shipped being set for use on a 100 V AC line power. To operate the instrument on other AC line voltage, its AC power input circuit (power connector B, tap, and fuse) must be converted referring to the following table.

Nominal tap	Applicable voltage range	Fuse	Connector
100 V 110 V 120 V	90 - 110 V 99 - 121 V 108 - 132 V	0.5 A	Connect the power connector B to the "100 V SYSTEM" pins.
220 V 230 V 240 V	198 - 242 V 207 - 253 V 216 - 264 V	0.3 A	Connect the power connector B to the "200 V SYSTEM" pins.



Connect the selector cord to the corresponding pin.

Fig. 4

### Notes:

- o Before performing AC line conversion, ensure that the AC power cord is disconnected from the AC power line outlet.
- o Use a cord and a plug which meet the requirements of the line power to be used.
- o The linefilter capacitor is not required to be changed.

## 4. OPERATING PROCEDURE

# 4.1 Preliminary Procedure (See Fig. 1)

Before turning-on the oscilloscope power, set the knobs on the front panel as shown in the following table:

	· · · · · · · · · · · · · · · · · · ·		
Item	No.	Setting	
POWER	1	OFF position	
INTEN	2	Mid-position	
FOCUS	(5)	Mid-position	
MODE	12	Press CHL button (12)	
POSITION	8	Mid-position	
VOLTS/DIV	14 16	GND position	
VARIABLE	15 17	CAL position	
AC - DC	20 21	AC position	
н, V	9	_ V position	
TIME/DIV	23	1 mS/DIV position	
VARIABLE	24)	CAL position	
TRIGGERING	26 27 28	Press CHL button (28).	
←→ POSITION	29	Mid-position .	

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Connect the power cord to an AC line outlet of the correct voltage and, then proceed as follows:

- 1) Turn the POWER switch (1) from the OFF position to the ON position. A click sound (power-on sound) is generated and the LED light turns-on at an upper left of the knob.
- 2) In about 10 seconds after the above, a bold horizontal trace line will be displayed on the CRT screen. Adjust the trace to an appropriate brightness with the INTEN knob 2.

If no trace is displayed within about 20 seconds, repeat setting of each knob as indicated in the above table.

- 3) Connect the signal of the CALIB (0.5 Vp-p) terminal to the vertical INPUT terminal (18) using the 942A Terminal Adaptor supplied.
- Set the VOLTS/DIV switch 14 in the 0.1 V position, so adjust the VARIABLE knob 15 that the displayed signal amplitude becomes 2 DIV, and make the displayed waveform stationary by turning the LEVEL knob 25. When this is done, a waveform as shown in Fig. 5 will be displayed on the CRT screen.

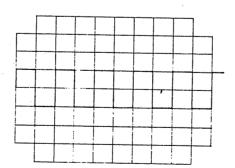


Fig. 5

- 5) So adjust the FOCUS knob (5) that the displayed waveform becomes sharpest.
- 6) So adjust the VOLTS/DIV switch 14 and TIME/DIV switch 23 that an appropriate number of peaks are displayed with an appropriate amplitude.
- 7) Align the displayed waveform with the graticule by adjusting the vertical POSITION knob (3) and horizontal POSITION knob (29), and determine the voltage (V) and period (T).

The above explanation is for the single-channel operation with CHL. The same explanation is applicable for the single-channel operation with CHR, simply by replacing "CHL" with "CHR". For the single channel operation with CHR, press the NORM button 27 of TRIGGERING selector or set it in the CHL + CHR state (press the CHL button 28 and NORM button 27 at the same time). The dual-channel operation and general operation methods of the oscilloscope are explained in the subsequent sub-sections.

# 4.2 Dual-trace Operation (STEREO operation)

Press the CHL button 12 and CHR button 11 of MODE selector at the same time to set the oscilloscope in the STEREO state. When this is done, another trace will be displayed on the CRT screen. This trace is of CHR. (The trace explained in the preceding sub-section is of CHL.) At this state of procedure, the CHL trace is the square wave of the calibration signal and the CHR trace is a straight line as no signal is applied to this axis yet.

Next, apply the calibration signal also to the CHR input terminal (19) in the same manner as done for the CHL channel, set the VOLTS/DIV switch (16) in the 0.1 V position, and so

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adjust the VARIABLE knob 24 and adjusting the vertical POSITION knobs 8 and 13 that dual traces as shown in Fig. 6 are displayed on the CRT screen.

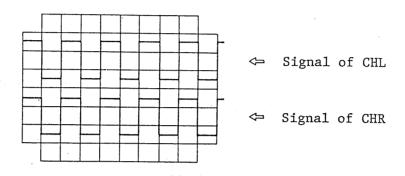
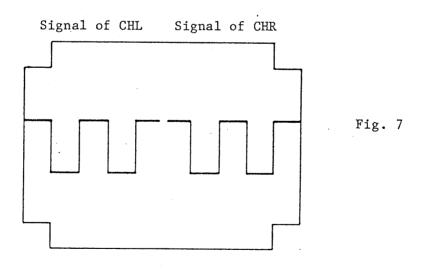


Fig. 6

When in the above state, by changing the MODE switch 9 from the V<sub>m</sub> state to the H<sub>m</sub> state and adjusting the vertical POSITION knobs 8 and 13, the signal waveforms of the CHL and CHR channels can be displayed to the left and to the right, respectively, on the same horizontal line as shown in Fig. 7. This is the horizontal STEREO operation.



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When in the STEREO operation, select a suitable triggering mode according to measurement — amplitude measurement, phase measurement, etc. For amplitude measurement, set the TRIGGERING selector in the CHL + CHR state (press the CHL button 28 and NORM button 27 at the same time); for phase measurement, set the TRIGGERING selector in the CHL state (press the CHL button 28).

When signals of mutually different frequencies are applied to the CHL and CHR channels, set the TRIGGERING selector in the NORM state (press the NORM button (27)).

This oscilloscope has eliminated the selector switch between CHOP and ALT modes for dual-trace operation. The sweep modes are switched being linked to the TIME/DIV switch (23). At the ranges the sweep speed is 1 msec/DIV or slower, switching is done in the CHOP mode; at the ranges the sweep speed is 100  $\mu$ sec/DIV or faster, switching is done in the ALT mode. When the TRIGGERING selector is set in the NORM state (27), switching operation in the ALT mode irrespective of setting of the TIME/DIV switch.

### 4.3 STEREO/X-Y Operation

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Set the MODE switch in the STEREO/X-Y state 10. With this simple procedure, the instrument operates simultaneous displaying of X-Y with vertical and horizontal dual-channel mode.

For the Y-axis, the CHR operates in the same electrical preformances and procedure. Regarding the X-axis, the frequency response becomes DC - 1MHz within -3 dB.

Apply the calibration voltage signal to both X and Y axis and adjust the VOLTS/DIV knobs of individual axis so that the signal waveforms of the CHL, CHR and Lissajous, figure as shown in Fig. 8 is displayed on the CRT screen.

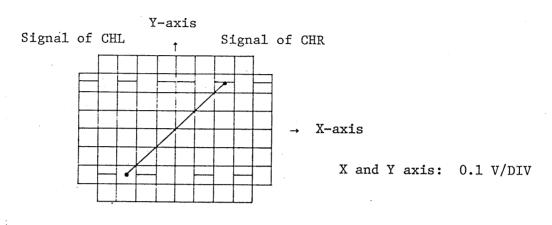


Fig. 8

The vertical POSITION control for CHR becomes effective for the displaying of CHR and X-Y, therefor it is possible to measure phase difference between X and Y axis of the wave-form with displaying of X-Y simultaneously.

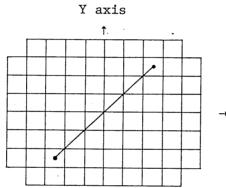
Note: For measurement of phase difference between X-axis and Y-axis, pay attention, they have within 3° phase difference of 50 kHz between them.

## 4.4 Only X-Y Operation

When both CHL  $\widehat{\mbox{11}}$  and STEREO/X-Y  $\widehat{\mbox{10}}$  buttons are pressed at the same time. The scope operates only X-Y mode.

This mode CHL POSITION 13 doesn't work, but X axis POSITION 29 work for X axis POSITION.

Apply the calibration signal to both X and Y axis and adjust the VOLTS/DIV knobs of individual axis so that a Lissalous figure as shown in Fig. 9 is displayed on the CRT screen



→ X axis

X and Y axis: 0.1 V/DIV

Fig. 9

### 5. METHODS OF MEASUREMENTS

## 5.1 Connection Method of Input Signal

The input impedance of the oscilloscope as viewed from the vertical input terminal is 1 M $\Omega$  with capacitance approximately 30 pF in parallel. When the probe (option) is used, the impedance increases to resistance 10 M $\Omega$  with capacitance approximately 12 pF in parallel.

There are various methods of connection between measured signal source and oscilloscope. The most popular methods are with regular wires, with shielded wires, with a probe, or with a coaxial cable. Suitable ones are used taking the following factors into consideration.

Output impedance of input signal source

Level and frequency of input signal

External induction

Distance between input signal source and oscilloscope

Types of input signals and connection methods are tabulated in the following:

Connection Type of input signal			General wire	Shielded wire	Probe	Coaxial cable	Others
Low	Low impedance	Near	0	O	0	0	
		Far		0		0	
	High impedance	Near		· Ø	0	0	
		Far		Ø .		Ø ·	
High frequency	Low impedance	Near			0	0	
		Far				0	
	High impedance	Near			0	Ø	
		Far					

(): Good, Ø: Fair)

### o Connection with regular wires:

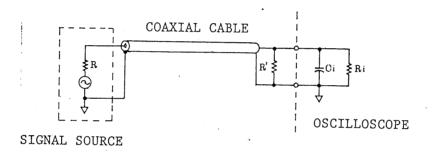
Set 942A Type Adaptor to the vertical input terminal and connect regular wires to the adaptor. This method is simple and the input signal is not attenuated. However it susceptible to induction noise when long wires are used or when the signal source impedance is high. Another disadvantage is a large stray capacity with respect to the ground. As compared with the case the 10: 1 probe (option) is used, larger effects are caused by the stray capacity.

### o Connection with shielded wire:

The use of a shielded wire prevents external induction noise. However, the shielded wire has as large stray capacitance as  $50~\rm pF/m-100~\rm pF/m$  and this method is not suitable when the signal source impedance is high or the measured signal frequency is high.

# o Connection with coaxial cable:

When the output impedance of the signal source is 50  $\Omega$  or 75  $\Omega$ , the input signal can be fed without attenuation up to high frequencies by using a coaxial cable which enables impedance matching. For impedance matching, terminate the coaxial cable with a 50  $\Omega$  or 75  $\Omega$  pure-resistive resistor corresponding to the characteristic impedance of the coaxial cable, as shown in Fig. 9.



R = R ' When R = 50  $\Omega,$  use a 50  $\Omega$  coaxial cable. When R = 75  $\Omega,$  use a 75  $\Omega$  coaxial cable.

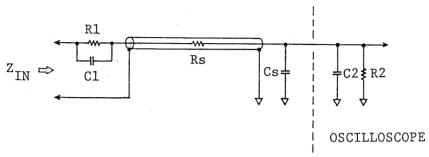
Fig. 9

### o Connection with probe:

0

A probe (example: 960 BNC Type Probe) with an attenuation ratio of 10: 1 is available as an option. The probe circuit and probe cable are shielded to prevent induction noise. The probe circuit makes up a wide-range attenuator in conjunction with the input circuit of the oscilloscope, thereby enabling a distortionless connection from DC to high frequencies. Then the probe is used, although the signal level is attenuated to 1/10, the input impedance

becomes very high (resistance 10 M $\Omega$ , capacitance approx. 20 pF) and the loading effect on the measured signal source is greatly reduced as explained in the following:



Rs = Series resistance of cable

Cs= Stray capacitance + cable capacitance

The probe makes up a wide-range attenuator with its resistor R1 which make up an attenuator circuit with respect to input resistor R2 of the oscilloscope and with its capacitor C1 which compensates for input capacitor C2 of the oscilloscope and stray capacitance (Cs) of the cable. The input impedance  $\mathbf{Z}_{\mathrm{IN}}$  is expressed as follows:

$$Z_{IN} = \frac{R1 + R2}{C (R1 + R2) + 1}$$

$$C = \frac{C1 \quad (C2 + Cs)}{C1 + C2 + Cs}$$

Attenuation factor A is expressed as follows:

$$A = \frac{R2}{R1 + R2} \quad ( = \frac{1 \text{ M}\Omega}{9M\Omega + 1M\Omega} = \frac{1}{10} )$$

### Precautions:

- o Observe the maximum allowable input voltages mentioned in Item 3.4 "Precautions in Operation."
- o Be sure to use the ground lead wire which accompanies the probe. When used in the dual-channel mode also, be sure to use the ground lead wires for individual channels.
- o Before commencing measurement, accurately adjust the phase of the probe without fail.
- o Do not apply unreasonably large mechanical shocks or vibration to the prove. Do not sharply bend or strongly pull the probe cable.
- o The probe unit and tip are not highly heat resistant.

  Do not apply a soldering iron to a circuit close to
  the point where the probe is left hooked up.

## 5.2 Voltage Measurement

ଓ **ଓ ଓ**  To measure an AC signal which has no DC component or to measure the AC component alone of a signal which has a DC component superimposed on the AC component, set the vertical input AC/DC selector switch (20, 21) in the AC position. To measure a signal which has a DC component, set the switch in the DC position.

Before commencing voltage measurement, set the VARIABLE attenuator knob ((15), (17)) to the CAL position and calibrate the sensitivity to the value indicated by the VOLTS/DIV selector ((14), (16)).

Apply the signal to be measured, display the signal with an appropriate amplitude on the screen, and determine the amplitude on the graticule. (For DC voltage measurement, determine the shifted distance of the trace.) The voltage can be known as follows:

(1) When measured signal is directly applied to input terminal:

Voltage (V) = Deflection amplitude (DIV)  $\times$  Indication of VOLTS/DIV switch

(2) When the 10 : 1 probe is used:

Voltage (V) = Deflection amplitude (DIV)  $\times$  Indication of VOLTS/DIV switch  $\times$  10

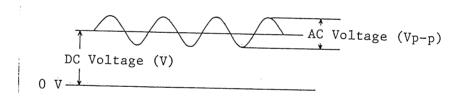


Fig. 11

(3) Comparison of amplitudes of CHL and CHR:

To compare the amplitudes of CHL and CHR, set the MODE switch 9 in the H state for the horizontal dual-trace operation and adjust the sweep at an appropriate speed. Denoting the amplitudes of CHL and CHR by A (DIV) and B (DIV) as shown in Fig. 12, the differential amplitude is calculated as follows:

Differential amplitude (dB) = 20  $\log \frac{B}{A}$ 

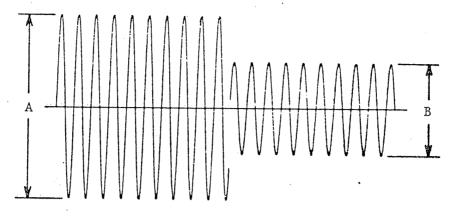


Fig. 12

## 5.3 Current Measurement (Voltage Drop Method)

Connect a small-resistance resistor (R) in series in the circuit in which the current (I) to be measured flows and measure the voltage drop across the resistor with the oscilloscope. The current is known from Ohm's Low as follows:

$$I = \frac{E}{R} \qquad (A)$$

The resistance should be as small as that it does not cause any change to the measured signal source.

In the above method, currents from DC to high frequencies can be measured quite accurately.

## 5.4 Time Measurement

Measurement of time interval

The time interval between any two points on the displayed waveform can be measured by setting the TIME/DIV VARIABLE knob 24 in the CAL position and referring to the indication of the TIME/DIV switch 23.

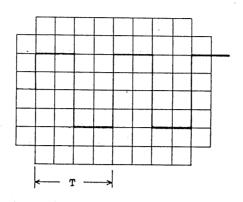


Fig. 13

Time T (sec) = Indication of TIME/DIV  $\times$  Horizontal span (DIV)

### 5.5 Frequency Measurement

o Frequency measurement by determining time (T) per one cycle of the displayed waveform:

Time T (period) is measured as explained in Item 5.4 and the frequency is calculated by using the following formula.

Frequency f (Hz) = 
$$\frac{1}{\text{Period T (sec)}}$$

o Frequency measurement with Lissajous figure (See Figs. 14 and 15.):

Set the MODE switch in the X-Y state so that the instrument operates as an X-Y scope. (See Item 4.3 "X-Y Operation.")

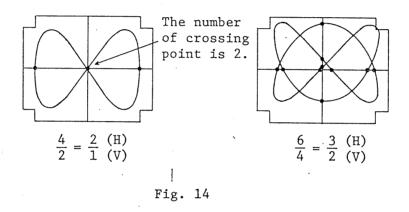
Apply to the X-axis a known frequency from a signal generator (SG) and to the Y-axis the frequency to be measured. So adjust the required controls that a pattern is displayed on the overall surface of the CRT screen. Then so adjust the frequency of the

signal generator that the displayed pattern becomes stationary as shown in Fig. 14. From the displayed waveform, the unknown frequency can be calculated as follows:

The number of crossing points

Unknown over horizontal scale line Frequency of frequency = 

(Hz) The number of crossing points generator (Hz) over vertical scale line



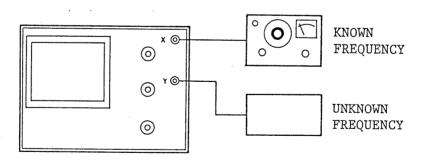


Fig. 15

#### 5.6 Measurement of Phase Difference

o Measurement with dual-trace operation (1):

Set the oscilloscope in the horizontal dual-trace STEREO mode by pressing the CHL (12) and CHR (11) buttons of the MODE switch at the same time and setting button (9) in the H state. Set the TRIGGERING selector in the CHL state (press button (28)), and apply the signal which is used as reference to the CHL input terminal (18) and the signal which is to be measured to the CHR input terminal (19). Make equal the amplitudes of the CHL and CHR channels by adjusting the VOLTS/DIV switches (14) and (16) and VARIABLE knobs (15) and (17). Align the vertical positions of the two signals by adjusting the vertical POSITION knobs (8) and (13).

Determine the vertical distance between reference signal and measured signal and denote the distance by B (DIV) as shown in Fig. 16. Also determine the signal amplitude and denote it by A (DIV). The phase difference ( $\alpha$ ) can be calculated with the following equation:

$$\alpha (°) = \frac{A}{B} \times (\pm 180°)$$

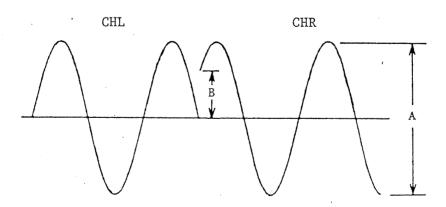


Fig. 16

## o Measurement with dual-trace operation (2):

Set the oscilloscope in the horizontal dual-trace STEREO mode as in the above measurement (1), and set the TRIGGERING selector in the CHL state (press button (28)). Apply the reference signal to the CHL input terminal (18) and the measured signal to the CHR input terminal (19). Determine the distances from the junction point of the two signals to the points where the two signals cross the horizontal base line and denote them by A (DIV) for CHL and B (DIV) for CHR as shown in Fig. 17. Denoting one cycle period of the signal by T (DIV), the phase difference can be calculated with the following equation:

$$\alpha (^{\circ}) = \frac{A - B}{T} \times 360^{\circ}$$

Where, if A < B, the measured signal is in a leading phase; if A > B, the measured signal is in a lagging phase; and if A = B the two signals are in the same phase.

For this measurement the displayed amplitudes of the two signals are not required to be made equal. The only requirement is that they are easily measurable. However, their zero levels must be accurately aligned.

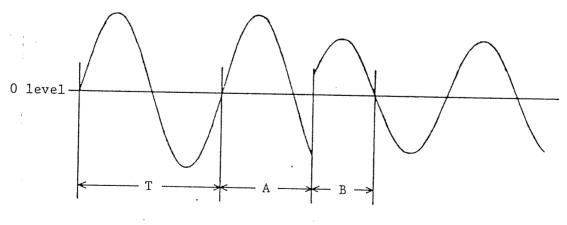


Fig. 17

o Measurement with dual-trace operation (3):

Set the TRIGGERING selector in the CHL mode (press button (28)), apply the reference signal to the CHL input terminal (18) and the measured signal to the CHR input terminal (19), and set the MODE switch button (9) in the V state in order that the oscilloscope operates in the vertical dual-trace mode.

Determine distance A (DIV) between the points where the two signal cross the base line as shown in Fig. 18. Denoting one cycle period of the CHL signal by T (DIV), the phase difference can be calculated with the following equation:

$$\alpha$$
 (°) =  $\frac{A}{T}$  × 360°

If A is in the left hand side of the measuring point of the reference signal, the measured signal is in a leading phase; if it is in the right hand side, the measured signal is in a lagging phase.

For this measurement the displayed amplitudes of the two signals are not required to be made the same, although it is recommendable to align the zero levels of the signals with the graticule lines for ease of measurement.

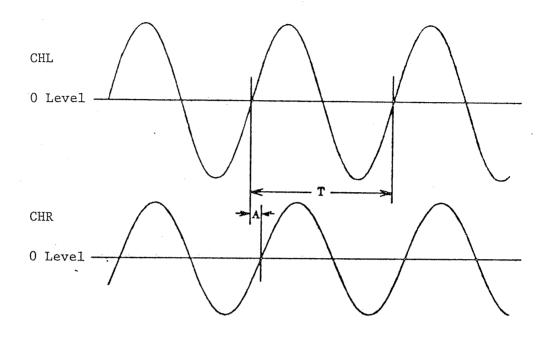


Fig.18

# o Measurement with Lissajous figure:

Set the oscilloscope in the X-Y mode by pressing the X-Y button  $\bigcirc 0$  of the MODE selector. Apply two signals of the same frequency (such as stereophonic signals) to the X-axis input terminal  $\bigcirc 18$  and Y-axis input terminal  $\bigcirc 19$ , and adjust equal the two signal amplitudes so that a Lissajous figure is displayed on the screen. Position the center of the Lissajous figure in the center of the screen, and determine distance A (DIV) between the two points where the Lissajous figure crosses the X-axis (or Y-axis) and determine amplitude B (DIV) of the Lissajous figure on the X-axis (or Y-axis). Phase difference  $\alpha$  can be calculated by the following equation:

Phase difference =  $SIN^{-1} \frac{A}{B}$ 

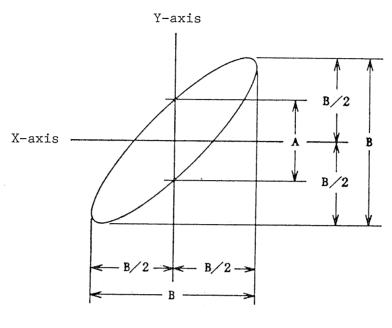


Fig. 19

For example, when the deflection amplitudes of the X-axis and Y-axis signals are set at 8 DIV, the phase difference can be known using Table 1 from the distance between the two points where the Lissajous figure crosses the X-axis (or Y-axis).

When the phase difference is within  $0^{\circ} \pm 90^{\circ}$ , the Lissajous figure is a slanted ellipse with its left side up; when the difference is within  $180^{\circ} \pm 90^{\circ}$ , the figure is a slanted ellipse with its left side up; when the difference is  $90^{\circ}$  or  $270^{\circ}$ , the figure is a circle; when the difference is  $0^{\circ}$ , the figure is a slanted line with its right side up; when the difference is  $180^{\circ}$ , the figure is a slanted line with its left side up.

Table 1

Distance (DIV) on X or Y axis	Phase difference (°)
0	0
0.1	0.7
0.2	1.4
0.3	2.2
0.4	2.9
0.5	3.6
1.0	7.2
1.5	. 10.8
2.0	14.5
2.5	18.2
3.0	22.0
3.5	25.9
4.0	30.0
5.0	38.7
6.0	48.6
7.0	61.0
8.0	90.0

Notes: The oscilloscope shipped from the factory is so set that, when it is operated in the horizontal dual-trace STEREO mode, the CHL signal is swept from the left end to the screen center and the CHR signal from the right end to the screen center. The user can change the sweep direction of the CHR signal so that the signal is swept from the screen center to the right end by setting of internal switch.

When the sweep direction has been changed as above, the phase difference measurement with dual-trace operation as described in Section 5.6 cannot be done because the sweep direction has been inverted by 180°.

To change the sweep direction, set the switch from "NORM" to "INV" on the pattern side of printed circuit board Al as shown in Fig. 20.

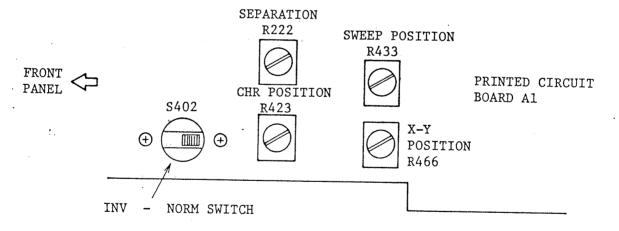


Fig. 20

#### 5.7 Measurement of Pulse Waveform Characteristics

A theoretically ideal pulse waveform is such that the signal changes instantaneously from a certain level to another level, held in this level for a certain period, and returns instantaneously to the original level. However, actual pulse waves are distorted. Nomenclature of distortions is given in Fig. 21.

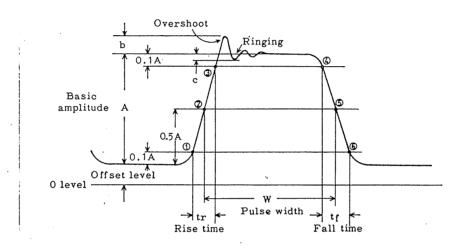


Fig. 21

Pulse amplitude: Basic amplitude (A) of pulse

Pulse width: Time between points 2 and 5 where

signal amplitude is 50% of basic amplitude

Rise time: Time between 10% basic amplitude point  $\bigcirc$ 

and 90% basic amplitude point ③

Fall time: Time between 90% basic amplitude point 4

and 10% basic amplitude point 6

Overshoot: Amplitude of the first maximum excursion

beyond basic amplitude. Expressed in

terms of  $b/A \times 100$  (%)

Ringing:

Oscillation which follows the first maximum excursion. Expressed in terms of  $c/A \times 100$  (%)

#### o Measurement of rise time:

The rise time of a pulse can be known by determining the value of  $t_r$  on the CRT screen in the method of "Time Measurement." It must be noted that  $t_r$  determined on the CRT screen includes the rise time of the oscilloscope itself. The closer the rise time of the oscilloscope  $(t_o)$  to the rise time of the measured pulse  $(t_n)$ , the larger is the error introduced. To eliminate this error, calculation should be done as follows:

True rise time 
$$t_n = \sqrt{(t_r)^2 - (t_o)^2}$$

where,  $t_r$ : Rise time measured on CRT screen  $t_o$ : Rise time of oscilloscope itself

(approx. 70 nsec)

For example, when a pulse wave with rise time 210 nsec (about 3 times of that of the oscilloscope) is measured on the CRT screen, the error is approximately 6%.

### o Measurement of Sag

Pulse waveforms may have slanted sections as shown in Fig. 22, other than those distoryions mentioned in Fig. 21. (For example, slants are caused when the signal is amplified with an amplifier which has poot low-frequency characteristics, resulting from attenuation of the low frequency component.) The slanted section (d or d') is called "sag" which is calculated as follows:

$$Sag = \frac{d}{A} \quad (or \frac{d'}{A'}) \times 100 \quad (\%)$$



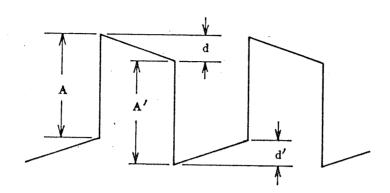


Fig. 22

Note: If the AC-coupling mode is used for measurement of a low frequency pulse, sags are caused. For measurement of low frequency pulses, use always the DC-coupling mode.

## 6. CALIBRATION

### 6.1 General

The oscilloscope should be calibrated at certain time intervals. Although calibration of overall performances is most recommendable, such partial calibration may serve the purpose that the time axis alone is calibrated when the time measuring accuracy is especially important or that the vertical axis alone is calibrated when the vertical sensitivity accuracy is of prime importance. After the oscilloscope has been repaired, overall calibration is required although it depends on the type of repair. For the repair service, contact manufacturer's representative in your area.

## 6.2 Check and Adjustment of DC Power Supply

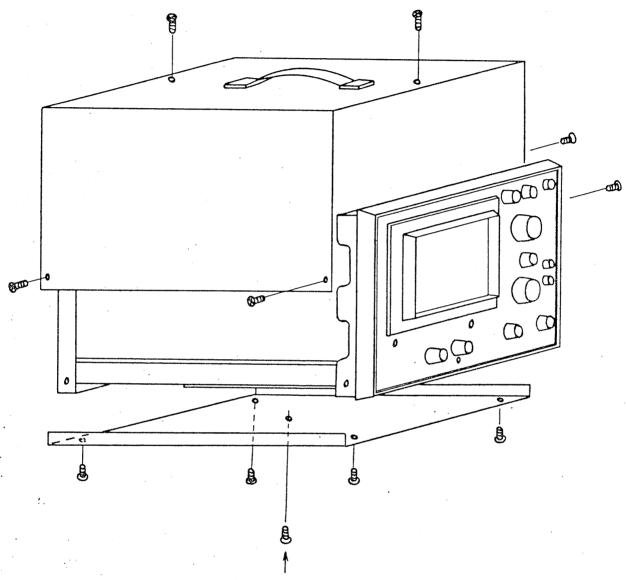
Before calibrating the oscilloscope, its DC supply voltages should be checked and adjusted. Check and adjust the +12V supply voltage first and the other supply voltages next. The supply voltages are shown in the following table, and the check and adjustment points are indicated in Fig. 24. For removing the case, refer to Fig. 23.

Nominal voltage	Voltage range	Check and adjustment points
+5V	+4.5 V - +5.5 V	TP-4
+12V	+11.95V - +12.05V	TP-1. Adjust the "+12VADJ"
-12V	-11.80V12.20V	TP-2
+200V	+180V - +230V	TP-3
-1500V	-1450V1550V	TP-5

For voltage check, measure the voltage between check point and ground using a reliable digital voltmeter. The +12V supply must be especially carefully adjusted because it provides a reference for other supplies. To measure the -1500V supply of which internal impedance is high, use a voltmeter of a high input impedance (10 M $\Omega$  or over).

Because adjustments of supply voltages largely affects vertical sensitivity and horizontal sweep time, the oscilloscope must be re-calibrated as explained in the subsequent paragraphs.

# \* Removing the case



HANDLE ESPECIALLY CAREFULLY SINCE THIS SCREW CLAMPS THE PRINTED BOARD.

Fig. 23

## As viewed from the bottom

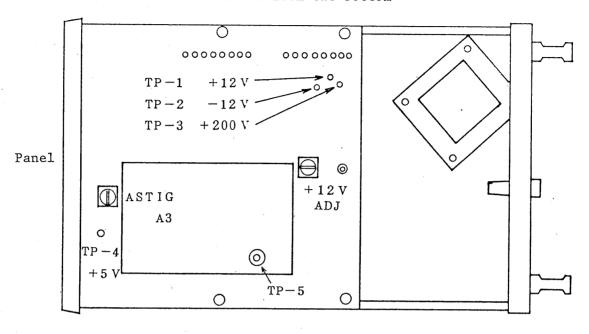


Fig. 24

## As viewed from the left hand side

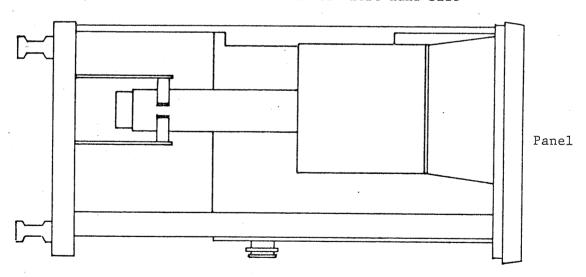
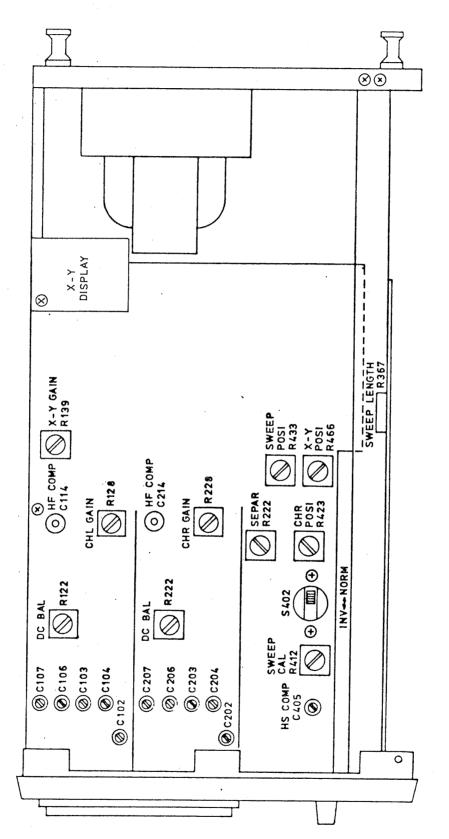


Fig. 25



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### 6.3 Adjustment of Vertical Axis

o Adjustment of DC BAL

This control is for minimizing the shift of the trace when the VARIABLE KNOB is turned.

- (1) Set the VOLTS/DIV switch 14 or 16 in the GND range and display the trace on the CRT screen.
- (2) Turning the VARIABLE knob, so adjust the DC BAL control that the sift of the trace becomes minimum. (See Fig. 26)

## o Calibration of sensitivity

This control is for adjusting the vertical gain so that the vertical deflection amplitude conforms with the value indicated by the VOLTS/DIV switch. For calibration, a pulse wave generator which can provide an output signal with a voltage setting accuracy of 0.5% or better at a frequency of 1 kHz should be used.

- (1) Set the pulse wave generator output at 40 mV and apply this signal to the vertical INPUT terminal.
- (2) Set the VARIABLE knob in the CAL position and the VOLTS/DIV switch in the 10 mV position, and so adjust the GAIN ADJ control (Fig. 26) that the deflection amplitude on the CRT screen becomes as set in 4 DIV.

When the above adjustment is made, other ranges also are automatically calibrated with an accuracy of  $\pm 5\%$  or better.

o Adjustment of input attenuator (input capacitance adjustment and phase compensation)

The VOLTS/DIV switch is a 1/10-step input attenuator. If the phase compensation of the input attenuator has been disturbed, the oscilloscope does not present the normal frequency response and the displayed waveform is distorted. If the input capacitance has been disturbed, the procedure of "Calibration of Probe" is required to be performed each time the range is changed. Refer to Item 5.1 "Connection Method of Input Signal", Para. "Connection with probe."

For phase characteristics adjustment, use a pulse generator which can provide a square wave which has no sags or overshoots or other distortions and which has a rise time of faster than 1  $\mu$ sec. Display this signal with an amplitude of 4 DIV at each range, and so adjust the phase compensation capacitor that the displayed square wave signal becomes the best waveform. For this adjustment, use a pulse repetition frequency of approximately 1 kHz.

For input capacitance adjustment, connect a low-range C-meter to the input terminal and so adjust the input capacitance compensation capacitor that the input capacitance at each range becomes  $30~\mathrm{pF}~\pm2~\mathrm{pF}$ .

For the above adjustment, set the oscilloscope in the operating state. The capacitors for respective ranges are shown in the following table.

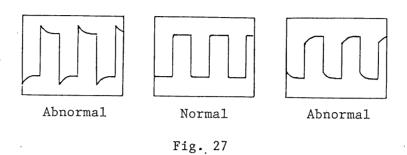
	(	CHL	CHR		
	Adjusting	capacitor	Adjusting capacito		
Range	Input capaci- tance	Phase compen- sation	Input capaci- tance	Phase compen- sation	
10 mV	C102	-	C202	_	
0.1 V	 C104	C103	C204	C203	
1 V	C107	C106	C207	C206	

o Adjustment of high frequency characteristics of vertical amplifier

Adjust the high frequency response characteristics of the vertical amplifier using a quality square-wave pulse signal of rise time 10 nsec or faster at pulse repetition frequencies 10 kHz and 100 kHz.

- (1) Apply the 10-kHz pulse signal to the input terminal, set the VOLTS/DIV switch at 10 mV and the TIME/DIV switch at 100  $\mu$ S, and so adjust the input signal amplitude that the signal is displayed with a deflection amplitude of 4 DIV on the CRT screen.
- (2) So confirm the leading edge of the square wave being flat by the HF COMP (C126) of the output circuit. (See Fig. 27.)
- (3) Apply the 100-kHz pulse signal to the input terminal, set the TIME/DIV switch at 1 µS, and so adjust the HF COMP (C114 for CHL or C214 for CHR) of the preamplifier that the leading edge of the square wave becomes flat. (See Figs. 26 and 28.)

By the above procedure, the 4-DIV square-wave pulse signal displayed on the CRT screen is adjusted to an ideal waveform.



Adjustment of HF COMP (C114, C214) of preamplifier

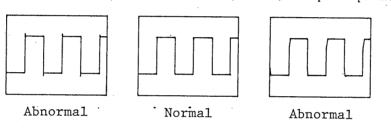


Fig. 28

6.4 Adjustment for Horizontal Dual-trace Operation

Set button 9 of the MODE switch in the H state and apply a sine wave signal of approximately 10 kHz to both CHL and CHR input terminals.

o Adjustment when sweep directions are from both ends of screen toward center of screen:

This adjustment includes SWEEP POSITION adjustment, SEPARATION adjustment and SWEEP LENGTH adjustment. (See Fig. 26.)

- (1) Set the horizontal POSITION knob (29) of Fig. 1 in a mid-position (the white dot of the knob set at the top position).
- (2) Set the TIME/DIV switch (23) at the 100  $\mu$ S position.
- (3) So adjust the SWEEP POSITION control that the CHL and CHR traces end at the center of the graticule.
- (4) So adjust the SEPARATION control that the two traces start at the two ends on the graticule.
- (5) So adjust the SWEEP LENGTH control (R367) that the ends of the CHL and CHR traces are spaced 0.2 DIV.
- (6) Check again the SWEEP POSITION and SEPARATION adjustments.
- (7) Apply a timer marker signal of 100  $\mu$ sec to the CHL and CHR input terminals.
- (8) So adjust SWEEP CAL control (R412, Fig. 26) that the periods of the displayed signal waveform conform with graticule lines. (See Section 6.5 Adjustment of Time base.)
- o Adjustment when sweep direction of CHL is from screen left end to screen center and that of CHR is from center to right end:

This adjustment includes CHR POSITION adjustment, and it must be done after the adjustment of the preceding section been done. To change the sweep direction, set the switch from "NORM" to "INV" on the pattern side of printed circuit board Al as shown in Fig. 29.

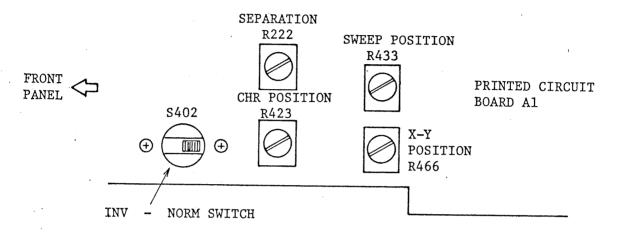


Fig. 29

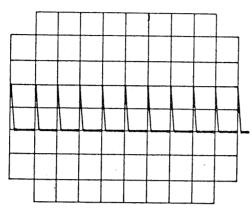
- (1) After the switch is set as required, apply a time marker signal of 100  $\mu$ sec to the CHL and CHR input terminals and set the TIME/DIV switch at the 100  $\mu$ S position.
- (2) When the starting position of the CHL sweep is deviated from the left end of the graticule, adjust the starting position to the end of the graticule by adjusting the horizontal POSITION knob.
- (3) So adjust the CHR POSITION control that the starting position of the CHR sweep is set at the center of the screen. When this is done, the distance between the end of CHL sweep and the start of CHR sweep should be approximately 0.2 DIV.

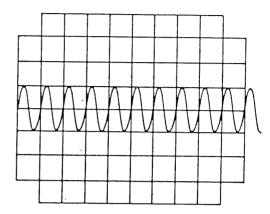
### 6.5 Adjustment of Time Base

This adjustment is for adjusting the actual sweep time of the trace to the value indicated by the TIME/DIV switch. For this adjustment, accurate time marker signals of repetion periods  $100~\mu sec$  and  $1~\mu sec$  or sine wave signals of frequencies 10~kHz and 1~MHz are required. When this adjustment is done, set the MODE switch 9 in the V<sub>200</sub> mode (vertical dual-trace mode) and keep the VARIABLE knob in the CAL position.

- (1) Set the TIME/DIV switch at the 100  $\mu$ S position, apply a time marker signal of repetition period 100  $\mu$ sec or a sine wave signal of frequency 10 kHz to the vertical input terminal, and so adjust the input signal amplitude or the oscilloscope sensitivity that the signal is displayed with an appropriate deflection amplitude on the CRT screen.
- (2) So adjust the SWEEP CAL control (Fig. 26) that the periods of the displayed waveform conform with graticule lines.
- (3) Next, apply a 1- $\mu$ sec time marker signal or a 1-MHz sine wave signal to the vertical input terminal signal and set the TIME/DIV switch at the 1  $\mu$ S position.
- (4) So adjust the HS COMP control (C405, Fig. 26) that the displayed waveform periods conform with graticule lines.
- (5) Check again for the  $100~\mu S$  range as Step (1) above.

By the above procedure, the sweep periods of the other ranges of the TIME/DIV switch also are calibrated to an accuracy of  $\pm 5\%$  or better. (Fig. 30)





Time marker signal

Sine wave signal

Fig. 30

## 6.6 Adjustment of X-axis

This procedure is for positioning of the X-axis and calibration of the X-axis when in the X-Y operation.

- o X-axis positioning when in X-Y operation
  - (1) For both CHL and CHR, set the VOLTS/DIV switch in the GND range and so set the horizontal POSITION knobs 29 that their white dot marks are positioned in the upright position (noon high position).
  - (2) Set the vertical MODE switch in the X-Y state ①, and so adjust the X-Y POSITION (R466, Semi-fixed resister, see Fig. 26) that the spot is displayed on the center line of the graticule.

o X-axis sensitivity calibration when in X-Y operation:

The vertical sensitivities of CHL and CHR are calibrated in Section 6.3. (For the X-Y operation, the X-axis sensitivity is required to be calibrated while Y-axis is not required to be calibrated because its vertical sensitivity has already been calibrated.) For calibrating the X-axis sensitivity, use the signal generator which has been used in Section 6.3 "Adjustment of Vertical Axis."

- (1) Set the oscillator output signal at 100 mVp-p and apply this signal to the X-axis input terminal.
- (2) So adjust the X-Y GAIN control (R139, Fig. 26) that the signal deflection amplitude becomes the full scale of the graticule.

## 6.7 Calibration of Probe (option)

As explained in Section 5.1, the probe makes up a kind of wide-range attenuator. Unless phase compensation is properly done, the displayed waveform is distorted causing measurement errors. Therefore, the probe must be properly calibrated before use. For probe calibration, use the signal of the calibration voltage output (CALIB, 0.5 Vp-p) terminal 6 of the front panel. (Fig. 31)

Connect the probe cord to the INPUT terminal of CHL or CHR and set VOLTS/DIV switch in the 0.1 V position. Connect the probe tip to the calibration voltage output terminal and so adjust the COMPENSATOR control with an insulated screwdriver that an ideal waveform as illustrated below is obtained.

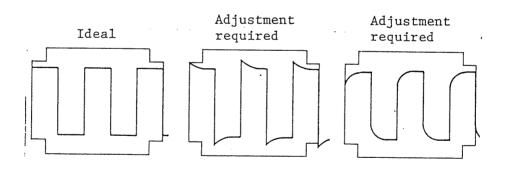
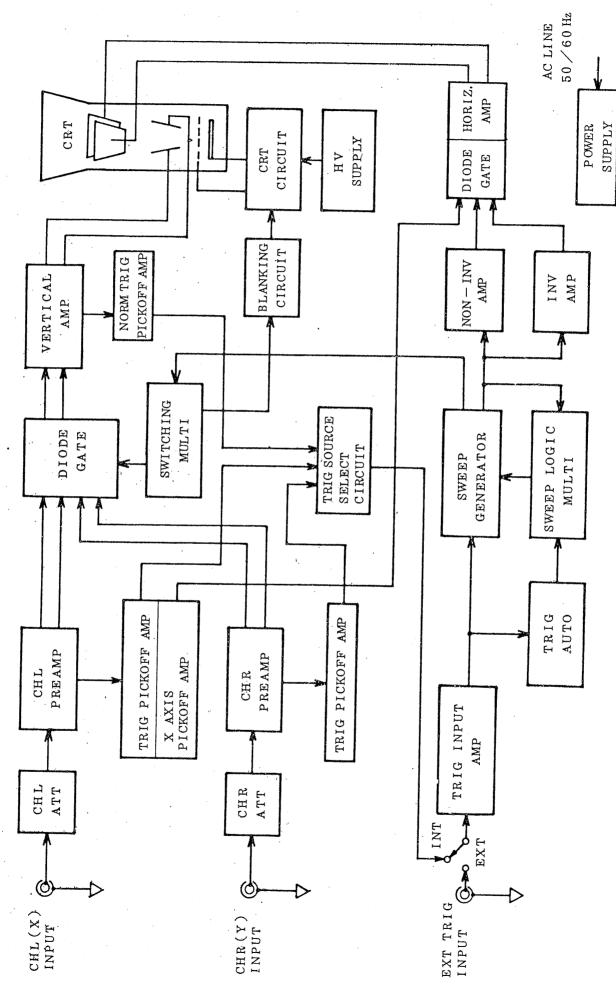


Fig. 32



Block Diagram

MODEL 5502AS

PARTS LIST

359	4	0.5		50700	1 5502A8		
A1	<u>-507-001</u>		1E	4 P.	ANEL FRONT 550, A	237801	
						د 3781S د	N24
		,				N24116S1	
A 6	-516-021		I E	4 N.	AME PLATE CAUTION HIGH VOLTAGE	491771	NZ
A8	-00C-19i		1E/		EAL FUSE 0.5A		N3
	• •					3111151	
. A8	-010-011		1 E	4 SI	EAL AC 100V	N344691	31
, вг	-050-041		1 E	Ç,	ASE 5520	394763	
		<del></del>					
В4	-050-051		1 .E	A PI	LATE BOTTOM	394752	
В6	-548-031		1 E	A PI	LATE REAR 5520	3105076	-
M RO	-505-561		1 F A		DON'T FOAME FEES		<del></del> .
	-050-121		1 .EA		RONT FRAME 5502	3118982	<del></del>
	-541-011				RONT FRAME 1	225152	
	-541-011		l EA		HIELD CRT	386314	
Co.	<u>-050-131</u>		3 <u> </u>	S.	HIELD PLATE BOXBOXO.3 BSP	4144147	
<b>C</b> 9	-050-141	2	EΑ	\ SH	HIELD PLATE 25X80X0.3 BSP	4144151	
D3	-050-441		L EA	<del></del>	RACKET PT	4134171	
D3	-050-461	1	EA	ВЕ	RACKET PUSH SW 5513	4143392	
	-050-471		2 EA	BR	RACKET_SHIELD_CRT_5520	4168861	
D3	-505-501	1	L EA	BR	RACKET P.C.B 5502	4152611	
D3	-505-502	2	E A	BR	RACKET VERT SW 5502	4155721	
D3-	-541-031	1	. EA	BR	RACKET CRT FOR 5512	385752	
D5:	-050-111	1	E A	ST	TAY I	394732	
D5·	-050-121	1	E A	ST	AY R	394724	
D5-	-050-131	1	. EA	ST	AY U	394742	
E7-	-000-061	1	EA	ST	AND 168X90A	388591	
к7-	-540-011		<u>E</u> A	co	NUPLING 6-6	4120022	
L3-	-020-021	2	EA	SP	PACER HEXAGON 3-10	447401	
L3-	-021-021	- 3	EA	SP	ACER HEXAGON 3-9 -5.5.+5	417312	
L3-	-021-041		EA		ACER HEXAGON 3-13.5 -6,+5	475671	·
Ml-	-002-011	4	FA		SET SCREW M3X0.5X4	-	
M8-	-000-391	4	ΕA		TYPE SPEED NUT SN-20 TO.45		
P5-	-050-041	1	ΕA		ND RUBBER 395	4143551	
Q3-	-505-501	2	EΑ	EX	TENTION SHAFT 6-80 5502	4155711	
Q4-	-548-011	1	FΑ		RRIFR P.C.B	4134323	
E R6-	-050-001	1	EΑ	PO	LY-BUKURO #9 440D-180W-420H	3147111	

		3594	05		507	,00 S	5502A8		
)		S3-050-141		1	EA_	SCALE PLATE		N34259B1	313
) }								4134641	3.1.3
	М	W4-986-C11		2	ΕA	942A TERMIN	AL ADAPTOR	4146412	41
)	*C	N6-000-041		1	EΑ		T 12/20 KNOB RED	4126211	41
	F	<u> 71-505-510</u>		_1	EA	OPERATION M	ANUAL J 5502		
)		Z5-C90-011		1	ΕA	CARTON 5520	WITH URETHANE	X 2 3146781	31
						•		4161121	41
)		Z6-090-011		۷.	ΕA	URETHANE FO	RM 245X2U0 552U	4161171	
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9				·	
	E6-000-011	2	EA	HANDLE BRACKET	470131
)	L4-257-011	1	EΔ	TERMINAL .	480774
	L4-257-021	. 1	EΔ	CUP TERMINAL .	480781
)	M8-000-201	. 2	EΑ	HANDLE SCREW	470123
•	N1-001-011		EA_	KNOB RIZSG GRAY	413037,
)	N1-001-031	3	EA	KNOB D22WG GRAY	4190051
	N2-000-011	3	EΔ	KNOB R14WR RED	4130331
)	P2-000-091	2	ΕA	BRACKET STAND A	364541
	P2-000-101	2_	EA	BRACKET STAND B	4101571
)	P2-000-291	1	ΕA	CAL TERMINAL	4145551
•	P2-000-321	8	ΕA	PUSH BUTTON 7.5X5.5 BEIGE	4158902
)	P2-000-331	. 9	ΕA	BEZEL FOR PUSH BUTTON	4157971
	P2-000-371		ΕA	PUSH BUTTON 7.5X5.5 RROWN	4158902
)	P2-050-111	. 1	EΑ	BEZEL SQUARE 5 INCH	225472
	P3-000-101	4	ΕA	HOLDER CORD 3W	3128561
)	P4-000-011	1	ΕA	BUSHING BDIA KG146	
	P4-000-551	1:0	FA	SK-BINDER SKB-1	UL
	P4-000-761	4	ΕA	SPACER FOR PUSH SWITCH 3MM	4127211
	P4-000-771	3	ΕA	SNAP BUSHING 6DIA	4127071
<b>)</b>	P4-050-051	1	EA	STRAIN RELIEF SR-4P-4	
· · · · · · · · · · · · · · · · · · ·	P5-000-031		ΕA	COVER RUBBER 9 DIA SGA-1	4167241
<b>.</b>	P5-000-151	4	ΕA	FOOT RUBBER 8X14X15	4101581
	P6-000-011	1	ΕA	HANDLE 200-21	455714
	P6-000-071	<del>2</del>	ΕA	HANDLE SHEET	
Е	R2-060-021	:0	CM	FELT 10W-2T-10001	455202
Ε	T4-000-131	45	EΑ	ADHESIVE TAPE, ACETATE, 5718 1	OHMYDAN
	X1-000-071	1	ΕA	MH6A HOLDER LED BLACK	7MMX36M
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9	21-11-0508	· 1	FΔ	1308X831_A
)	30-10-8381	. 8	EΑ	2SA838-B HFE 7U-140
	30-10-8441	11	ΕA	2SA844-D HFE 250-500+55V,0.1A,0.3W
)	30-20-8341	1	ΕA	2SB334-Y 60V,3A,30W,100-200
<del></del>	30-30-9451	3.6	FA	2SC945-Q HEE 135-270
)	30-31-7301	2	EA	2SC1730-L HFE 60-120
	30-31-8431	2	EΑ	2SC1843-E HFE 400-800
)	30-31-9071	. 8	ΕA	2 SC1 907
	30-32-3710	11	EA_	2SC2371-L HEF 100-200
)	30-40-8802	2	EΑ	2 SD8 80-Y 60 V , 3 A , 3 Ú W , 1 0 0 - 2 0 0
	31-20-0306	2	EΑ	2SK30A-0 FET
)	31-20-1171	1	ΕA	SKI17-BL FET
	31-90-0041	2	FA	UPA63H-1 DUAL FFT.IVGS1-VGS21 30MV
)	32-11-5880	56	ΕÀ	181588 DIODE VF 30V IF 0.5A P 300MW
_	32-30-0830	2	EA	1883 VR 250V,IO 200MA HV SW
)	32-90-0523	13	ΕA	S5277J DIODE 600V IA
	32-90-0550	. 1	EA_	VIIM DIODE
<b>)</b>	32-90-0940	1	EΔ	SIVB20 BRIDGE DIODE
•	32-91-0060	1	ΕA	RD7.5JB 7.0-7.9V
)	32-91-1200	2	EA	OZBZ3.9 DIODE
	32-92-0056	3	FA_	RD5.6JB2 5.5-5.8V
)	32-92-0360	4	EΑ	HZ36-2L 35.3-36.8V
	34-40-0070	1	EΑ	TA7179P DUAL +/ 15V TRACKING RAGULATOR
)	35-60-0000	1	ΕΑ	TC4011BP QUAD 2-INPUT NAND GATES
•	35-70-0001		FΔ	SN74LSOON QUAD 2-INPUT POSI-NAND
	35-70-3081	1	EA.	SN74LSO8N QUAD 4-INPUT POSI-AND
	35-70-0101	1	EA .	SN74LS10N TRI 3INPUT POSI-NAND
)	35-70-0731	1	EΔ	SN74LS73N DUAL J-K FLIP=FLOP
	35-70-0741	1	FA	SN74LS74N DUAL D-FLIP-FLOP FDGF-TRIG
)	35-70-0761	1	EΑ	SN74LS76N DUAL J-K M/S F-F WITH P/C
•	37-00-0060	1	ΕA	TLG-105 LED-LMP-GREEN
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····	42-44-1270		<u> </u>		J3C 2 MOHMF
<u> </u>	42-72-1220	·····	EΔ		4 220 OHM F
•	42-72-2100	ż	EA	CM1/	4 1K OHM F
	42-72-3101	. 2		CM1/	+ IU.IK OHM F
<u></u>	42-72-3180	1	<u> </u>	CM1/4	+ 18K OHM F
<u> </u>	42-72-3220	5 			4 22K OHM F
	42-72-4111	2	EΑ		+ 111K OHM F
)	42-74-4333	1		CM1/2	2 333K UHM F
<del></del>	42-74-4750	1	EA_	CM1/2	750K OHM F
	42-74-4900	2	ΕA	CM1/2	2 900K DHM F
	42-74-4990	. 2	EΑ	CM1/2	990K OHM F
:	42-74-5100	4	ΕA	CM1/2	2 IM OHM F
	42-94-4110	1	FΑ	RF55-	-YO-11CK OHM-E
	42-94-4470	2	EΔ	RE55-	-YQ-470K OHM-F
	44-91-3680	4	EΔ	MOR-1	B 68K OHM J
	44-92-6820	3	ΕA	MOR-2	2B 82 OHM J
	44-9;-;270	1	FΔ	MOR-2	B 7K OHM J RESIST . FIX
· · · · · · · · · · · · · · · · · · ·	45-35-2202	3	ΕA	V16L4	+ 7X5 PH2 N15S B 2K OHM
	45-35-4102	. 1	EA	Vi6L4	7X5 PH2 N15S B 100K OHM
	45-37-1200	3	EA	VZ103	KTLI 200 OHM
7	45-37-7100		<u>FA</u>		KTL1 1K DHM
	45-37-2200	1	EΑ	VZ103	KTL1 2K OHM
	45-37-4500	1	EΔ	VZ103	KTL1 5K OHM
	45-37-3100	. 2	ΕA	VZ103	KTL1 10K OHM
	<u>45-37-32-00</u>	2	FA	VZ103	KTL1 ZOK OHM
	45-37-4200	1	EΑ	VZ103	KTL1 200K OHM
	45-42-4200	1	ΕA	V016L	12-7 PH3C N 20KS BC-B 200K DHM
	45-42-5100	1	EA		12-7 PH3C N ZOKS BC-B IM OHM
•	48-14-1500	1	EA_	TMICK	PH 500 0HM
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. •	<u> 40-27-500</u>	68_	EA_	NASI/4 O OHM JUMPER PARTS
0	40-27-3132	7	EΑ	NASI/4SìO OHM J RESIST, FIX, CAR
	40-27-0222	4	EΑ	NAS1/4S22 OHM J RESIST, FIX, CAR
0	40-27-0332	7	EA	NASI/4S33 OHM J RESIST.FIX.CAR
	40-27-:472	1	FΔ	NASI/4S47 OHM J RESISI, EIX, CAR
0	40-27-0682	2	EΔ	NAS1/4S68 OHM J RESIST, FIX, CAR
•	40-27-1102	. 32	EΑ	NAS1/4S100 OHM J RESIST, FIX, CAR
0	40-27-1152	4	ΕA	NASI/4SI5U OHM J RESIST, FIX, CAR
	40-27-1182		<u>EA</u>	NASI/45180 OHM J RESIST, FIX, CAR
0	49-27-1222	20	ΕA	NAS1/4S220 OHM J RESIST, FIX, CAR
	40-27-1272	7	EΑ	NAS1/4S270 OHM J RESIST, FIX, CAR
0	40-27-1332	9	EA	NASI/45330 DHM J RESIST, FIX, CAR
·	40-27-1392	9	EA_	NASI/45390 OHM J RESIST, FIX, CAR
0	40-27-1472	8	EΑ	NASI/4S470 OHM J RESIST, FIX, CAR
	40-27-1562	. 6	ΕA	NAS1/4S560 DHM J RESIST, FIX, CAR
0	40-27-1822	1	ΕA	NASI/4S820 OHM J RESIST, FIX, CAR
	40-27-2102	6	EA_	NAS1/4S1K OHM J RESIST, FIX, CAR
0	40-27-2122	4	EΑ	NAS1/4S1.2K OHM J RESIST, FIX, CAR
	40-27-2152	2	ΕA	NAS1/4S1.5K OHM J RESIST, FIX, CAR
0	4C-27-2182	5.	ΕA	NASI/4SI.8K OHM J RESIST, FIX, CAR
·•	40-27-2222		FΔ	NAS1/4S2.2K OHM J RESIST.FIX.CAR
0	<pre>40-27-2272</pre>	11	EΔ	NAS1/452.7K DHM J RESIST.FIX.CAR
	40-27-2332	7	EΑ	NAS1/4S3.3K OHM J RESIST.FIX.CAR
0	40-27-2392	15	EΑ	NASI/483.9K OHM J RESIST, FIX, CAR
	40-27-2472	5_	ĒA_	NASI/4S4.7K OHM J RESIST, FIX, CAR
0	40-27-2562	11	EΔ	NAS1/4S5.6K OHM J RESIST, FIX, CAR
	40-27-2682	1	ΕA	NAS1/4S6.8K OHM J RESIST, FIX, CAR
0	40-27-2822	9	ΕA	NASI/4S8.ZK OHM J RESIST, FIX, CAR
	40-27-3102	31_	<u>FA</u>	NASI/4SIOK OHM J RESIST.FIX.CAR
0	40-27-31,2	3	EΑ	NAS1/4S12K OHM J RESIST, FIX, CAR
.*	40-27-3222	9	ΕA	NAS1/4S22K OHM J RESIST, FIX, CAR
9	40-27-3392	4	ΕA	
	40-27-3472	1	FΔ	
0	40-27-3682	3	EΑ	NAS1/4S68K OHM J RESIST, FIX, CAR
	40-27-4102	5	ΕA	NAS1/4S100K OHM J RESIST, FIX, CAR
0	40-27-4222	2	ΕA	
**************************************	40-27-4472	4	ΕA	
0	40-27-8472	Z	EΑ	
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-	40-37-0101	1	EΔ	RD1/2PXJ15 OHM RESIST, EIX, CAR	
-	40-37-1331	2	ΞA	RD1/2PXJ330 OHM RESIST, FIX, CAR	
	40-37-2101	1	ΕA	RD1/2PXJ1K OHM RESIST, FIX, CAR	
	40-37-4471	· . 1	EA	RDI/2PXJ4.7K OHM RESIST, FIX, CAR	
	40-37-3101	1	ΕA	RD1/2PXJ10K OHM RESIST, EIX, CAR	
	40-37-3471	1	EΑ	RD1/2PXJ47K OHM RESIST, FIX, CAR	
.*	40-37-4101	3	ΕA	RD1/2PXJ1GCK OHM RESIST, FIX, CAR	
	40-37-4221	3	ΕA	RD1/2PXJ220K OHM RESIST,FIX,CAR	
	40-37-5101	1	F.A.	RD1/2PXJIM OHM RESIST, FIX, CAR	
	40-37-5221	10	ΕA	RD1/2PXJ2.2M OHM RESIST, FIX, CAR	
	40-37-5681	2	EΑ	RD1/2PXJ6.8M OHM RESIST, FIX, CAR	·
	50-43-6500	1	ΕA	HPF-1H-102-F 0.001MF F%	
	50-43-6570	1	FΔ	HPF-1H-104-F 0.1MF F%	
	50-45-0500	. 2	EΑ	CQ92MC1H103J CAP, POLYEST 0.01MF J% 50WV	
	50-67-0060	5	ΕA	CQ92MC 1H/2A 104K 0.1MF K% CAP, POLYEST	
	50-87-3500		E A	CF922L2G104KX MET,D POLYEST 9.1MF 400V	
	50-97-3620	1	<u>EA</u>	MET 3D223M MET D POLYEST J. U22ME 2000V	5.7
	50-97-3640	. 3	EΑ	MF1 3D473M MET'D POLYEST 0.047MF 2000V	S79
	52-01-2265	2	EΑ	ECK-F1H221KB CERAMIC 220PF K 50WV	
•	52-01-3305	č	EΔ	ECK-DZH471KB CERAMIC 470PF K 500WV	
	52-01-3325	1	ΕA	FCK-D2H681KB CERAMIC 680PF K 500WV	
	52-01-3365	2	EΑ	ECK-D2H152KB CERAMIC 1500PF K 500WV	
	52-01-3385	2	ΕA	ECK-D2H222KB CERAMIC 2200PF K 500WV	
	52-02-3466	1	EΔ	ECK-DZHIO3MD CERAMIC U. 61MF M 500WV	
	52-05-1498	2	ΞA	FCK-F1F1047F CERAMIC O.IMF Z 25WV	
	52-25-2468	11	EΑ	ECK-FIH103ZF CERAMIC 0.01MF Z 50WV	
	52-06-2215	1	ΕA	DD107 CH 820J 50V CERAMIC 82PF 50WV	
	52-06-2225	6	EΑ	DD107 CH 101J 50V CERAMIC 100PF 50WV	***************************************
	52-06-2245	4	ĒΑ	DD109 CH 151J 50V CERAMIC 150PF 50WV	
	52-06-2265	6	ΕA	DD111 CH 221J 50V CERAMIC 220PF 50WV	
	52-06-3030	-1	ΕA	ECC-D2H030CC CERAMIC 3PF C 500WC	
	52-06-3102	4	ΕA	ECC-DZH100FC CERAMIC 10PF K 500WV	
	52-06-3125	1	FA	FCC-D2H150KC CERAMIC 15PF K 500WV	
	52-06-3185	9	ΕA	ECC-D2H47GKC CERAMIC 47PF K 500WV	
	52-77-1000	2	ΕA	ECK-DDS102MD CAP, CERAMIC 250VAC1000PF	

	3600	03	5 <b>û</b> 7	700 9 5502AS
	54-00-00, 2			CHI/VD : TO I/III/ TO UT I COURT
<del> </del>	54-00-0121	5	<u> </u>	SM16VB-270 16WV.7UMF.10X13 *465690*
	54-00-0311			SM25 VB-100 25WV100MF +8X12 *406384*
	•	18	EA	SM50VB-10 50WV10MF.5X11 *407488*
	54-00-0312	1	EA.	SM50VB-22 50WV2ZMF.7X11 *407585
	54-06-33, 4	3_	F.A	SM50VB-470 50WV470MF.16X25 *494658*
	54-01-0311	3	EA	CEUST1H100. 50WV10MF,6.3X12.5
	54-71-1020	1	EΑ	315T-47 CAP, ELECT 315WV47MF
	54-80-1020	14	EA	350VB-4.7 CAP, ELECT 350WV4.7MF
	57-13-1130		<u>FA</u>	CTZ81C 3-10PF CFR.TRIM BROWN
	57-10-1110	1	E'A	CTZ81E 4-20PF CER•TRIM RED
	57-10-1140	2	EΑ	CTZ81G 6-50PF CER TRIM GREEN
	57-10-1180	4	EA	ECV-1ZWU4X53 1.5PF-4PF BLACK CER, TRIM
	57-10-1190	4_	<u>FA</u>	ECV-17W1GX53D
	60-45-0010	1	EΔ	PT 5509 100,120V X2 S7706882 S
				S7706902
	M 66-21-0060	1	ΕA	RUTATION COIL S7901413
	*C 91-80-5460	1	FΔ	WIRE KIT COIL ROTATION \$7301611
	80-98-0380	2	EA	S21P 224/RV 389000404 4155731
	80-98-0390	1	ΕA	S21P 245/RV 5502A 329012600 4157611
	81-01-0380	2	ΕA	SPJ222 TYPE L 389607925
	81-03-0040	1	FA_	FUM3-6-10 SWITCH BUTTON 489844
· .	81-04-0190	1	ĒΔ	SUB41 PUSH SWITCH 389607926 S7900351
	82-44-00:50	1	EA.	SSF22-08.SWITCH, SLIDE
	82-93-0000	1	ΕA	SD24L5 S U9SF-0 15S
	83-30-1021	3_	E.A.	BNC-071 CONNECTOR RECEPTACLE
	84-51-0000	1	ΕA	AFOUT, FUSE HOLDER, SHONIN NO, AFOOT-AC2
	84-80-0200	3.	EΑ	5287-2A FLAT WAFER ASSEMBLY 5-02
	84-80-0201	3	EA ·	5287-34 FLAT WAFER ASSEMBLY 5-03
	84-80-0203	1_	FΔ	5.87-54 FLAT WAFER ASSEMBLY 5-05
	84-80-0235	2	EΑ	5271-08A FLAT WAFER ASSEMBLY 3.96-08
	84-80-0250	2	ΕA	3022-02A FLAT WAFER ASSEMBLY 2.5-2
	84-80-0251	1	EA	3022-03A FLAT WAFER ASSEMBLY 2.5-3
	84-80-0256	111	EΔ	3022-10A FLAT WAFER ASSEMBLY 2.5-10
	84-80-0635	2	ĒΑ	5145-08AH SOLDER TYPE SIDE ASSY 3.96-8
	85-10-0020	1	EΑ	AC PLUG WITH CORD 2.5-M GRAY
	87-40-0010	8	ΕA	SET PIN 1.2X12L SN MEKKI
	87-40-0040	20	E A	RT-07T-1.3B DIAMOND CONNECTOR PIN
	99-00-0103	1	EΔ	FUSE-0.5A F-1065 6.4-30

an and the same of the same of

<u>}                                    </u>						•			
}		-	3601	0.2	50	700 11	55Q2A\$		
	<u>E</u> _	_Y_	M2-000-011	6_	EA	BIND SCRE	W MZXO•4X4 B-NI		
	E	Υ	M2-000-021	4	EΔ	•	W M2X0.4X6 B-NI		
	E	Υ	M2-000-071	2	ĒΑ	BIND SCRE	W M3XQ.5X4 B-NI		
	E	Υ	MZ =000=101	9	ΕA		W M3X0.5X10 B-NI		
	<u>_</u>	_Y_	M2-000-171	10	ΞΔ	•	W M4X0.7X8 B-NI		
	E	Y	M2-000-231	4	EΑ		W M4X0.7X32 B-NI		
	E	Y	M2-000-301	1	EΑ	BIND SCRE	W M4X0.7X14 B-NI		
	E	Υ.	M2-000-391	44	ΕA	BIND SCRE	W M3X0.5X6 B-N1		
	E_	Y_	M2-001-081	13	EA_	SARA SCRE	W M3X0.5X6 S-7MC2		
	. E	Υ	M2-014-021	2	ΕA	BIND TAPP	ING SCREW 3X8 S-ZN		
	Ε	Υ	M2-014-041	10	EΑ	BIND TAPP	ING SCREW 3X12 S-ZN	1	
	E	Y	M4-000-031	10	EΔ	NUT HEXAG	ON M3NXO.5 B-NI		
	E_	Y	M4-000-041	3	FΔ	NUT HEXAG	ON M4NXO.7 B-NI		
			M4-000-141	1	EΑ	NUT M6NXC	.75 B-NI	4126732	
	٤	Y	M5-000-011	4	ΕA	WASHER M2	W B-NI	,	T
	E	Y	M5-000-031	15	ΕA	WASHER M3	M B-NI		
	<u>E</u> _	Y	M5-001-011	8_	<u> </u>	SPRING WA	SHER 2 SW B-NI		
	Ε	Y	M5-001-031	19	EΔ	SPRING WA	SHER 3 SW B-NI		
	Ε	Y	M5-001-041	6	EΑ	SPRING WA	SHER 4 SW B-NI		
<del>,</del>			M5-001-061	1	EA	SPRING WA	SHER 6 SW B-NI		
	E	Y	M5-002-051	5	<u> FA</u>	LOCK WASH	ER 3 LW EXT		
	E	Υ	M5-002-071	6	EΑ	LOCK WASH	ER 4 LW EXT		
			90-50-1930	1	EΑ	PCB-S 551	3A4 LINE VOLTS CHAN	GE N442041	4:
								N442731	4)
			90-50-3010	1	FA_	PC BOARD-	S X-Y DISPLAY	N449651	4 i
			90-50-3020	1	EΑ	PCB-S A1	VERT/HOR AMP 5502A	N241101	
				-		·	·	N241111	2
			90-50-3030	1	ΕA	PCB-S AZ	TRIG/CRT 5502A	N164781	<u></u>
	·							N104791	1
			90-50-3040	1.	ΕA	PCB-S A3	ASCCC WS-ADDM	N349561	31
	Ε	Y	91-02-0001	10	CM.	TUBE . IRRA	X V2 CLEAR, 1. ODIA, 0	•4THICK	
	E	Υ-	91-02-0002	10	CM	TUBE . IRRA	X VŽ CLEAR, Ž. IDIA, S	•4THICK	
	E	<u>Y</u>	91-02-0003	10	<u>CM</u>	TUBE . IRRA	X V2 CLEAR, 2, 9DIA, 0	•5THICK	
	E	Υ	91-02-0004	50	CM	TUBE, IRRA	X V2 CLEAR, 4.1DIA. 0	•5THICK	
	E	Y	91-02-0005	50	CM	TUBE , IRRA	X V2 CLEAR,5.2DIA,0	•5THICK	7.00
			91-80-5551	1	ΕA	WIRE KIT	55U2A	S79 <del>U3</del> 222	S79
		···						\$7903242	

MODEL 5502AS

SPARE PARTS LIST

KIKUSUI ELECTRONICS CORPORATION

CONTRACT NO. 14-472/27431/00092/2-0040/84 APPENDIX NO. 13

Q'TY	/	AMOUNT														
		Q'TY	•	^		: 5	K.			01		C/		(		$\wedge$
57		ILLUSTRATIONS	SILLCON PNP TR	MATRINICHTA	SILICON NPN TR	(H)XX/H)	SILICON TR.	TOSHIBA	SILICON ,	$N_i \kappa_i C$	SILICON NPN TR	1, 5, C	SILICON NPN.	LOW NOWS	SILICON NPN	UHE AMP HITACH
MACHINERIES/EQUIPMENT NAME	OSCILLOSCOPE STOZA-B		IT 300MHB TYP.	VCBO 30V IC 30mA, HFF 90-140		HFE 250-500, 551, 0,1A, 0,3W		HFE 100-200 60T, 3A, 30W	IT STOMME TYP VCBO 60V, ICIOUMA	HFE 135-270	FILLOOMHE TYP VCBO 30V, IESOMA SILICON NPN	HFE 60-120	IT 100MHB TYP VCBU 60V, IC100MA SILICON NPN	HFE 400-800	57 1100 MHZ TYP	VCBO 30V, Jc SOMA HFE 40
PARTIAL OBJECT INDEX NO.		PARTS PARTS DESCRIPTION NO.	30-10- TRANSISTOR	8381 2SAB3B-B	30-10-	844/ 25A844-B	30-20-	8341 2538834-7	30-30-	9451 25C945-Q	30-3/-	7301 2551730-6	30-3/-	843/ 25C/B43-E	30-31-	9071 2SC1907

.S.	
PARTS	
WEARING	
AND	
SPARE	

PARTIAL OBJECT INDEX NO.	MACHINERIES/EQUIPMENT NAME	31		Q'TY
$\sim$	OSCILLOSCOPE SSOZA-S	2		/
PARTS DESCRIPTION		ILLUSTRATIONS	Q'TY	AMOUNT
	57 FOMHS TYP. VCBG 3007 IC100ms	300 V ICIOOMA SILICON NPN TR.	•	
2552391-6	HFE 100-200	V,8,C	$\Rightarrow$	
		SILICON NPN TR		
250A80-Y	HFE 100-200, 60T, 3A, 30W,	TOSHIBA	N	
		J. FET		
28K30A-0	VGS-50V, IG/OMA, PB 100 mW	T0.5H1BA	C/	
	8m 40~15m3	J. FET	)	
28K117-BL	VGS-50V, IG 10MA, PD 300 M.	TOSHIBA		
PUAL F,E,T	195 60V ID 30mA	BUAL J. FET		
UPA 63H-1	INGS1 - 14521 30MV	/ K	~	
		SILICON DIODE		
1815181	VF30V IF O.SA P 300MW	T05H1BA	0	
	HIGH VOLTAGE SWITCHING.	SILICON DIODE		
	VR 250V, IO ROOMA HV SW	HITACHII	N	

CONTRACT NO. 14-472/27431/00092/2-0040/84 APPENDIX NO. 13

QTY	/	AMOUNT						٠								
		Q'TY	•	¥		_	-		-	7		~		1		· ~
		ILLUSTRATIONS	SYLICON DIODE	TOSHIBA	SILICON DIODE	HITACHI	BRIDGE RECTIFIER	SHINDENGEN	ZENER DIODE	N, 8, C	ZENZA DIODZ	708H1BA	ZENJR DIODE	N. M. M.	ZENER DIODE	HITACHI
MACHINERIES/EQUIPMENT NAME	S502A-S		12		2		8	VEM LOCK			<b>X</b> \		M		M	,
MACHINERIES	OSC1LLOSCOPE	OUTLINE SPEC.		600T, 1A		1300V, 0.5A		VRM 200V, IO O.6A.	VOLTAGE RANGE	70-291	VOLTAGE RANGE.	3,4-4,67	VOLTAGE RANGE	5,5-5,81	VOLTAGE RANGE.	35.3-36,40
OBJECT INDEX NO.	$\sim$	PARTS DESCRIPTION		552777		VIIM	BRIDGE DIODE.		ZENZR DIODE	RD PISTB		02823.9		RD SIGJB2		H836-2L
PARTIAL OBJECT		PARTS NO.	32-50-	0523	32-90-	0550	32-90-	0 740.	32-91-	0900	32-91-	(200	32-92-	0056	32-92-	0360

LIST	
PARTS	1
	1
WEARING	
AND	-
PARE	
	1

PARTIAL OBJECT INDEX NO.	MACHINERIES/EQUIPMENT NAME			Q'TY
×	02614201COPB 5502A-S	62		
PARTS NO. PARTS DESCRIPTION		ILLUSTRATIONS	Q'TY /	AMOUNT
		+, - 15V REG		
0070 TA7179P	+001 UNSUMMA TCVO 6,007/2/60	TOSHIBA		
35-60- INTEGLATED CIKIT	QUAD 2-MPUT			
0000 TC401/BP	POSY- NAND GATE	TONHIBA	1	
37-00- LED	FORWARD CURRENT 45MA DC			
201-571 0900	LED-LAMP-GREEN	TOSH18A	1	
			,	
79-00-				
· FUSE	F-7142 0.3A 5,2X 2011/12	NATO PARTS	1	;
			· ·	

APPENDIX NO. 13

MACHINE INDEX NO.  MACHINE DESCRIPTION  DIMENSIONS & WEIGHT	2
MACHINE INDEX NO.  MACHINE DESCRIPTION  DIMENSIONS & WEIGHT	
4.30~5.60 6.  (A.30~5.60 6.  (A.30	
PARTS INDEX NO. PARTS NO. PARTS DESCRIPTION Q	
	TY
30-10-8441 25A844-D 4	<u>этү</u> У
30-10-844/ 25A844-D  MACHINE INDEX NO. MACHINE DESCRIPTION	
MACHINE INDEX NO. MACHINE DESCRIPTION  DIMENSIONS & WEIGHT	
MACHINE INDEX NO. MACHINE DESCRIPTION	
MACHINE INDEX NO. MACHINE DESCRIPTION  DIMENSIONS & WEIGHT kg	

APPENDIX NO. 13

PARTS INDIX NO.	PARTS NO.	PARTS DESCRIPTION	1 0:50
3 17/110 111017 110.		PARTS DESCRIPTION	YT'D
	30-20-8341	23B834-Y	-/
MACHINE INDEX NO.		MACHINE DESCRIPTION	
DIMENSIONS & WEIGHT		kg	•
	·	(F) X(M) X(H)	
CHARACTERISTICS & DRAWI	NG/PHOTOGRAPI	1_	
1.00~1.77   X X X X X X X X X X X X X X X X X X	6~4.82 1.00~1.50 0~1.14 2.04~2.92		6
PARTS INDEX NO.	PARTS NO.	PARTS DESCRIPTION	arr
	30-30-9451	25C945-Q	10
MACHINE INDEX NO.		MACHINE DESCRIPTION	
			· ·
DIMENSIONS & WEIGHT			
		kg	
		inm (L) X (W) X (G	)
CHARACTERISTICS & DRAWI	NG/PHOTOGRAPH	<u>4</u>	
.4.30 ~ 5.60 ¢ ,			
0.29~ 11 2 3 1 2 3 1 2 3 1 3 2 3 1 3 2 3 1 3 2 3 1 3 3 3 3 1 3	2.95~4.40		

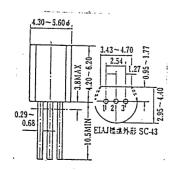
- 7, E
- 2. C
- 3. B

APPENDIX NO. 13

### SPECIFICATION OF SPARE PARTS

	• • • • • • • • • • • • • • • • • • • •	y		
PARTS INDIX NO.	PARTS NO.		PARTS DESCRIPTION	Q'TY
	30-31-730/	25C1730-L		2
MACHINE INDEX NO.		MA	ACHINE DESCRIPTION	
DIMENSIONS & WEIGHT				
<del></del> -	<u></u>	(L) X		
CHARACTERISTICS & DRAWI	NG/PHOTOGRA			
4.30~5.604				
0.29~ NI EIAJI: 法外示: 5	2.95-4.40			0
1, E 2, C				
3. 8				
PARTS INDEX NO.	PARTS NO.		PARTS DESCRIPTION	Q'TY
	30-31-8431	28C/843-E	•	2
MACHINE INDEX NO.	Ţ	MA	ACHINE DESCRIPTION	
DIMENSIONS & WEIGHT			kg	
		inm (L) X	.mm (W) X(H)	

#### CHARACTERISTICS & DRAWING/PHOTOGRAPH



- t, E
- z, c
- 3, B

APPENDIX NO. 13

#### SPECIFICATION OF SPARE PARTS

PARTS INDIX NO.			
FARTS INDIA NO.	PARTS NO.	· PARTS DESCRIPTION	Q'TY
	30-31-9011	2301907	2
MACHINE INDEX NO.	-	MACHINE DESCRIPTION	
DIMENSIONS & WEIGHT		kg	
<del></del> .	. •		
CHARACTERISTICS & DRAWIN	NG/PHOTOGRA	РН	
1. E  2. C  3. 8	95~4.40		
PARTS INDEX NO.	PARTS NO.	PARTS DESCRIPTION	Q'TY
TAITIS INDEX NO.			Q I I
	<u> </u>		
	30-32-3710		4
MACHINE INDEX NO.	<u> </u>		4
MACHINE INDEX NO.	<u> </u>	25c 2371-L	<i>y</i>
MACHINE INDEX NO.  DIMENSIONS & WEIGHT	<u> </u>	25c 2371-L  MACHINE DESCRIPTION	* 
	<u> </u>	25c 2371-L	* 
	30-32-3910	25c 2371-L  MACHINE DESCRIPTION  kg  inm (L) X(W) X(ii)	* 
CHARACTERISTICS & DRAWIN  8.5MAX 28MA  10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	30-32-37/0	25c 2371-L  MACHINE DESCRIPTION  kg  inm (L) X(W) X(ii)	4

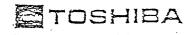
3, B

APPENDIX NO. 13

PARTS INDIX NO.	PARTS NO.		ARTS DESCRIPTION"		עד׳ם
_=			Wild Description	· · · · · · · · · · · · · · · · · · ·	411
	30-40-8802	25D880-1		•	2
MACHINE INDEX NO.		MAC	HINE DESCRIPTION		
DIMENSIONS & WEIGHT				-	
DIMENSIONS & WEIGHT				kg	
	-		(W) X	<u>mm</u> (H)	
CHARACTERISTICS & DRAWI	NG/PHOTOGRAP	<u>'H</u>			
9.50~10.66 9.50~10.66 254 254 254 271 1.00~1.77   1.23   1.00	1 "				0
2. c				•	
3. E					
PARTS INDEX NO.	PARTS NO.	P	ARTS DESCRIPTION		OTY
PARTS INDEX NO.	PARTS NO. 3/-20-0306	2 S K 3 O A - O	ARTS DESCRIPTION		2 2
	İ	25K30A-0			1
PARTS INDEX NO.  MACHINE INDEX NO.	İ	25K30A-0	ARTS DESCRIPTION  HINE DESCRIPTION		1
	İ	25K30A-0			2
MACHINE INDEX NO.	İ	25K30A-0 MACI	HINE DESCRIPTION	kg	2
MACHINE INDEX NO.  DIMENSIONS & WEIGHT	3/-20-0306	2 S K 3 O A - O  MACI		kg mm (ii)	2
MACHINE INDEX NO.	3/-20-0306	2 S K 3 O A - O  MACI	HINE DESCRIPTION		2
MACHINE INDEX NO.  DIMENSIONS & WEIGHT	3/-20-0306	2 S K 3 O A - O  MACI	HINE DESCRIPTION		2

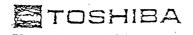
APPENDIX NO. 13

PARTS INDIX NO.	PARTS NO.	· PAR	TS DESCRIPTION"		QTY
	3/-20-1171	25K117-BL			1
MACHINE INDEX NO.		MACHI	NE DESCRIPTION		
DIMENSIONS & WEIGHT				kg	
	•	(L) X	(W) X	mm (H)	
CHARACTERISTICS & DRAWIN	NG/PHOTOGRAS	<u>.</u> Р <u>Н</u>			
\$ 5.1MAX 0.4 0.4 0.4					$\bigcirc$
1.27   127	1. D 2. G 3. S				
PARTS INDEX NO.	PARTS NO.	PAR	TS DESCRIPTION		QTY
<u> </u>	<del></del>	, 			
	31-90-0041	μpA63H-1			2
	31-90-004		NE DESCRIPTION		2
	31-90-004		NE DESCRIPTION		2
			NE DESCRIPTION	kg	2
MACHINE INDEX NO.		MACHII	NE DESCRIPTION  .mm (W) X	kg mm (ii)	2
MACHINE INDEX NO.  DIMENSIONS & WEIGHT		MACHII			2



APPENDIX NO. 13

PARTS INDIX NO.	PARTS NO.		PARTS DESCRIPTION"		QTY
	32-11-5880	151588			10
MACHINE INDEX NO.		M	ACHINE DESCRIPTION		
DIMENSIONS & WEIGHT	<u> </u>			•	
		(L) X	(W) X	kg(H)	
CHARACTERISTICS & DRAWII	NG/PHOTOGRA				
\$05 NIN 98 NIN 98 NIN Y 98 ONI N. 18 ON NIN Y 98 ON NI	Ø1.9илх.				
A PLANT TO CONTRACT MANAGEMENT AND A PROPERTY OF					
PARTS INDEX NO.	PARTS NO.		PARTS DESCRIPTION		מדץ
PARTS INDEX NO.	PARTS NO.	/5583	PARTS DESCRIPTION		2 2
PARTS INDEX NO.  MACHINE INDEX NO.			PARTS DESCRIPTION		
MACHINE INDEX NO.					
MACHINE INDEX NO.			IACHINE DESCRIPTION	kgkg	
MACHINE INDEX NO.	32-30-0830	ı <u>nm (</u> L) X	IACHINE DESCRIPTION		
MACHINE INDEX NO.  DIMENSIONS & WEIGHT  CHARACTERISTICS & DRAWIN	32-30-0830	ı <u>nm (</u> L) X	IACHINE DESCRIPTION		
MACHINE INDEX NO.  DIMENSIONS & WEIGHT  CHARACTERISTICS & DRAWII	32-30-0830	ı <u>nm (</u> L) X	IACHINE DESCRIPTION		
MACHINE INDEX NO.  DIMENSIONS & WEIGHT  CHARACTERISTICS & DRAWII	32-30-0830	ı <u>nm (</u> L) X	IACHINE DESCRIPTION		
MACHINE INDEX NO.  DIMENSIONS & WEIGHT  CHARACTERISTICS & DRAWII	32-30-0830	ı <u>nm (</u> L) X	IACHINE DESCRIPTION		
MACHINE INDEX NO.  DIMENSIONS & WEIGHT  CHARACTERISTICS & DRAWIN	32-30-0830	ı <u>nm (</u> L) X	IACHINE DESCRIPTION		



APPENDIX NO. 13

· · · · · · · · · · · · · · · · · · ·				*	
PARTS INDIX NO.	PARTS NO.	· PAR	TS DESCRIPTION"		Q'TY
	32-90-0523	S5271J			4
MACHINE INDEX NO.		МАСНІЛ	E DESCRIPTION	·	
-					
DIMENSIONS & WEIGHT				kg	
*		mm (L) X		<u>mm</u> (H)	
CHARACTERISTICS & DRAWIN	NG/PHOTOGRAPH	<del></del>			
カソード・マーク (1円) SL (1円	26 MIN.				
PARTS INDEX NO.	PARTS NO.	PAR	TS DESCRIPTION		YTD
	72-90-0550	V11M			·.
MACHINE INDEX NO.		MACHIN	NE DESCRIPTION		
-					
DIMENSIONS & WEIGHT		inm (L) X	.mm (W) X	kg mm (ri)	
CHARACTERISTICS & DRAWIN	VG/PHOTOGE ARE			***************************************	
SAME OF STREET OF STREET	TG/TOTOGRAPI	<u>.                                     </u>			
0.775-0.8 ¢  !!  ii  ii  5 MAX	0.775~0.8¢			•	

APPENDIX NO. 13

PARTS INDIX NO.	PARTS NO.	PAR	TS DESCRIPTION		Q'TY
	32-90-0940	S1 V B 20			1
MACHINE INDEX NO.	1		NE DESCRIPTION		
MACHINE INDEX NO.		MACAII	4E DESCRIPTION		······································
DIMENSIONS & WEIGHT	• ,			kg	
: ;		mm (L) X	<u>mm</u> (W) X	mm (H)	
CHARACTERISTICS & DRAWI	NG/PHOTOGRAS	<u>.</u>	•		
	•				
e de la compansa de l					
	7				,,,,,
16**** HENTINGS	1 1				(_
PSVIZ €	<u></u>				
		•			
1 2 2					
1_1_1_	• .				
				•	
PARTS INDEX NO.	PARTS NO.	PAF	RTS DESCRIPTION		מידץ
	32-9/-0060	RD 7.5JB			1
MACHINE INDEX NO.		MACHI	NE DESCRIPTION		
					1
DIMENSIONS & WEIGHT					
				kg	
	·	inm (L) X	(W) X	mm (ri)	
CHARACTERISTICS & DRAWII	NG/PHOTOGRAS	<u>'H</u>			
φ0.5					
NIMS 25MIN.			•		٠
4.2MAX.					
				•	
φ2.0MAX.		·			
Z					
71r Zi					
25MIN.	• , •				



APPENDIX NO. 13

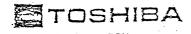
MACHINE DESCRIPTION    Machine Description	2
kg	
	()
	$\bigcirc$
PARTS DESCRIPTION	Q'TY
5,6182	
MACHINE DESCRIPTION	
ke	
(L) X(W) X(G)	
- )	MACHINE DESCRIPTIONkg

APPENDIX NO. 13

and the second			
PARTS INDIX NO,	PARTS NO.	· PARTS DESCRIPTION	YT'D
	32-92-0360	HZ36-2L	2
MACHINE INDEX NO.		MACHINE DESCRIPTION	
		Per description of the second	
DIMENSIONS & WEIGHT			•
	* .	kg	
	-	mm (L) X mm (W) X mm (H)	
CHARACTERISTICS & DRAWI	NG/PHOTOGRAPH	<u>.</u>	
en en en en en en en en en en en en en e			
_			
NING 12.06MAX		•	
2.0 ¢MAX			(
4.2MAX-			
+ 7			
- As /			
NIIW			
<u> </u>			
PARTS INDEX NO.	PARTS NO.	PARTS DESCRIPTION	Q'TY
	34-40-0070	TA7179P	1
MACHINE INDEX NO.		MACHINE DESCRIPTION	
		· · · · · · · · · · · · · · · · · · ·	
			*
DIMENSIONS & WEIGHT		li-	
		kg	
	***************************************	<u>nnm (L) Xmm (W) Xmm (ri)</u>	
CHARACTERISTICS & DRAWI	NG/PHOTOGRAPH	<u>-</u>	
14 13 12 11 10 9 8	<del></del>		
	& S MAX.		
31.0	19		
1234557			
19.9 MAX.	7.62±0.25		
200	× (8° )		
	_1     <u>                                </u>		
· 80 / / / / / /	1 80		
z 1.4±0.15	0.25 -0.05		
1.4±0.15 0.5±0.15 0.2 MAX.	7.62~ 3.80		

APPENDIX NO. 13

· ·					
PARTS INDIX NO.	PARTS NO.	PAR	TS DESCRIPTION"		YTD
	35-60-0000	TC 4011 BP			1
MACHINE INDEX NO.			NE DESCRIPTION		
DIMENSIONS & WEIGHT					
		(L) X		kg mm (H)	
CHARACTERISTICS & DRAWIN	NG/PHOTOGRAPH	<u> </u>			
14 13 12 11 10 9 8 Q2 MAX. RLO RLO 199 MAX.	1N 20 WAX. 65 WAX. 65 WAX. 65 WAX. 65 WAX.		· .		
2.54±0.25 5.08 P 7.62 P 10.16 F 15.70	0.25-0.10 0.25-0.10 0.25-0.10 0.25-0.10 0.25-0.10				
	. XAM 08.B	PAR	TS DESCRIPTION		ר ביי
229 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1		PAR TLG -105	TS DESCRIPTION		0°TY
229 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1	PARTS NO.	TLG-105			1
254 250 250 250 250 250 250 250 250 250 250	PARTS NO.	TLG-105			1
254 250 250 250 250 250 250 250 250 250 250	PARTS NO.	TLG-105			1
PARTS INDEX NO.  MACHINE INDEX NO.	PARTS NO.	TLG-105		kg mm (a)	1
PARTS INDEX NO.  MACHINE INDEX NO.	880 MAX.	TLG-105  MACHIN	NE DESCRIPTION	kg	1



APPENDIX NO. 13

The state of the s			
PARTS INDIX NO.	PARTS NO.	PARTS DESCRIPTION	Q'TY
	99-00-0005	FUSE	1
MACHINE INDEX NO.	1.	MACHINE DESCRIPTION	
DIMENSIONS & WEIGHT	·	kg	
	-		
CHARACTERISTICS & DRAWI	NG/PHOTOGRAS	<del>2H</del>	
PARTS INDEX NO.	PARTS NO.	PARTS DESCRIPTION	QTY
TARTS INDEX NO.	172113 110.		
		•	
MACHINE INDEX NO.		MACHINE DESCRIPTION	
MACHINE HABEA NO.			
			ン
DIMENSIONS & WEIGHT		lea.	
		kg	
	<del></del>	inm (L) Xmm (W) Xmm (ri)	
CHARACTERISTICS & DRAWI	NG/PHOTOGRA	<u>РН</u>	
	•		
	•		